

LINEAR UNITS MODULAR LINEAR ACTUATORS



LINEAR UNITS

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BELT DRIVEN LINEAR UNITS

BR-S / BT-S







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GUIDE

FEATURES

- High speed High acceleration
- Large stroke lenghts
 Good repeatability

Linear Unit	Dynamic load capacity		Max. travel speed	¹ Max. profile length	Max. repeatability	Dimen	sions
	Cy [N]	Cz [N]	[m/s]	[mm]	[mm]	² Width [mm]	³ Height [mm]
BR-S 40	46	510	6	3000	± 0.08	40	52
BR-S 65 S	99	000	6	6000	± 0.08	65	85
BR-S 65 L	19	800	6	6000	± 0.08	65	85
BR-S 80 S	17	100	6	6000	± 0.08	80	100
BR-S 80 L	34	200	6	6000	± 0.08	80	100
BR-S 110 S	24	800	6	6000	± 0.08	110	129
BR-S 110 L	49	600	6	6000	± 0.08	110	129
BT-S 40	3400	1700	10	6000	± 0.08	40	52
BT-S 65 L	8600	4400	10	6000	± 0.08	65	85
BT-S 80 L	17100	9000	10	6000	± 0.08	80	100
BT-S 110 L	31000	14000	10	6000	± 0.08	110	129

¹ For lengths over the stated value in the table above please contact us. ² Profile ³ Profile + carriage

BR-D





DRIVE



FEATURES

- High speed
 High acceleration
 Large stroke lenghts

- Good repeatability
 High load capabilities
 High flexural rigidity

Linear Unit	Dynamic load cap	pacity	Max. travel speed	¹ Max. profile length	Max. repeatability	Dimensions		
	Cy [N] Cz [N]		[m/s]	[mm]	[mm]	² Width [mm]	³ Height [mm]	
BR-D 90 S	4620		5	6000	± 0.08	90	40	
BR-D 90 L	9240		5	6000	± 0.08	90	40	
BR-D 110 S	19800		6	6000	± 0.08	110	50	
BR-D 110 L	39600		6	6000	± 0.08	110	50	
BR-D 145 S	34200		6	6000	± 0.08	145	65	
BR-D 145 L	68400		6	6000	± 0.08	145	65	
BR-D 200 S	49600		6	6000	± 0.08	200	100	
BR-D 200 L	99200		6	6000	± 0.08	200	100	

¹ For lengths over the stated value in the table above please contact us. ² Profile ³ Profile + carriage

BR-E



Linear Unit	Dynamic load capacity	Max. travel speed	¹ Max. profile length	Max. repeatability	Dimensions		
	Cy [N] Cz [N]	[m/s]	[mm]	[mm]	² Width [mm]	³ Height [mm]	
BR-E 40 S	9900	3	5960	± 0.1	40	78	
BR-E 40 L	19800	3	5960	± 0.1	40	78	
4							

¹ For lengths over the stated value in the table above please contact us² Profile ³ Profile + carriage

BELT DRIVEN LINEAR UNITS

BR-Z



Linear Unit	Dynamic le	oad capacity	Max. travel speed	¹ Max. profile length	Max. repeatability	Dimensions		
	Cy [N] Cz [N]		[m/s]	[mm]	[mm]	² Width [mm]	³ Height [mm]	
BR-Z 40	46	10	5	3000	± 0.08	40	88	
BR-Z 65	198	800	5	6000	± 0.08	65	143.5	
BR-Z 80	342	200	5	6000	± 0.08	80	178.5	
BR-Z 110	496	600	5	6000	± 0.08	110	241	

¹ For lengths over the stated value in the table above please contact us² Profile ³ Profile + carriage

BALL SCREW DRIVEN LINEAR UNITS



SR-D



Linear Unit	Dynamic load capacity	Max. travel speed	¹ Max. profile length	Max. repeatability	Dimensions		
	Cy [N] Cz [N]	[m/s]	[mm]	[mm]	² Width [mm]	³ Height [mm]	
SR-S 40	4620	0.97	2920	± 0.01	40	52	
SR-S 65	19800	1.12	2920	± 0.01	65	85	
SR-S 80	34200	2.5	5480	± 0.01	80	100	
SR-S 110	49600	1.6	5850	± 0.01	110	129	

¹ For lengths over the stated value in the table above please contact us² Profile ³ Profile + carriage



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DRIVE

GUIDE

FEATURES

- High repeatability High load capabilities High flexural rigidity

Linear Unit	Dynamic load capacity	Max. travel speed	¹ Max. profile length	Max. repeatability	Dimen	Dimensions		
	Cy [N] Cz [N]	[m/s]	[mm]	[mm]	² Width [mm]	³ Height [mm]		
SR-D 90 S	4620	0.97	750	± 0.01	90	40		
SR-D 90 L	9240	0.97	750	± 0.01	90	40		
SR-D 110 S	19800	1.12	1500	± 0.01	110	50		
SR-D 110 L	39600	1.12	1500	± 0.01	110	50		
SR-D 145 S	34200	2.5	1800	± 0.01	145	65		
SR-D 145 L	68400	2.5	1800	± 0.01	145	65		
SR-D 200 S	49600	1.6	2200	± 0.01	200	100		
SR-D 200 L	99200	1.6	2200	± 0.01	200	100		

¹ For lengths over the stated value in the table above please contact us? Profile ³ Profile + carriage

In order to improve the products in this catalog the specifications are subject to change without notice.

CHARACTERISTICS

BR-S and BT-S Linear Units with toothed belt drive and compact dimensions provide high performance features such as, high speed, good accuracy and repeatability. They can easily be combined to multi-axis systems.

Excellent price-/performance ratio and quick delivery time are ensured.

The compact, precision-extruded aluminum Profile from 6063 AL with integrated Zero-backlash Ball rail guide system, allows high load capacities and optimal cycles for the movement of larger masses at high speed.

For very high speeds, up to 10m/s, the Track Rollers (journal Bearings) of the type BT-S are particularly suitable.

In the Linear Units BR-S and BT-S is used a pre-tensioned steel reinforced AT polyurethane timing toothed belt. In conjunction with a Zero-backlash drive pulley high moments with alternating loads with good positioning accuracy, low wear and low noise can be realized.

The in the Profile slot driving Polyurethane timing belt protects all the parts in the Profile from dust and other contaminations. As optional, a corrosion-resistant protection strip is available.

The aluminum profile includes T-slots for fixing the Linear Unit and for attaching sensors and switches. Also, a Reed switch can be used here.

Different carriage lengths with central lubrication port, allow easy re-lubrication of the Linear Unit and allow the possibility to attach additional accessories on the side.

For the Linear Units BR-S and BT-S various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.



i The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0.35 mm/m; Max. torsion = 0.35 mm/m; Angular torsion = 0.2 mm/40 mm; Parallelism = 0.2 mm

STRUCTURAL DESIGN

BR-S Series



- 1 Drive block with pulley
- 2 Corrosion-resistant protection strip (available also without protection strip)
- 3 AT polyurethane toothed belt with steel tension cords
- 4 Carriage; with built in Magnets
- 5 Aluminium profile-Hard anodized
- 6 Linear Ball Guideway
- 7 Central lubrication port; both sides
- 8 Tension End with integrated belt tensioning system



BT-S Series

- 1 Drive block with pulley
- 2 Corrosion-resistant protection strip (available also without protection strip)
- 3 AT polyurethane toothed belt with steel tension cords
- 4 Carriage; with build in Magnets
- 5 Aluminium profile-Hard anodized
- 6 Track Roller (journal Bearing)
- 7 Two hardened steel Round guide (58/60 HRC)
- 8 Central lubrication port; both sides
- 9 Tension End with integrated belt tensioning system

HOW TO ORDER

Series Prefix:BR BT	
Size:	
Series Suffix:	
Absolute stroke [mm]:	
Carriage Version:	
Type of drive pulley:	
03: Without drive unit 10: Pulley with journal (without Keyway) 20: Pulley with journal on both sides (with Keyway)	
Drive journal position: L: Journal on left side R: Journal on right side X: Both sided or none	
Protection cover: — 0: In profile groove guided Polyurethane toothed belt 1: Corrosion-resistant protection strip	
Version:S: Special Version	

1: Standard Single Carriage

2: Dual Carriage

General Technical Data

Linear Unit	Carriage length	i _{loa}	Dynamic ad capac	: ity	i	Dynamic moment		For	Max. ı ces	permissil	ble loads Momen	ıts	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	** Min. stroke
	Lv [mm]	C [N]	Cy [N]	Cz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-S 40	92	4610	/	/	28	90	90	3850	3850	14	75	75	0.28	± 0.08	3000	2876	25
BT-S 40	92	/	3400	1700	20	21	25	1015	1090	13	14	7.6	0.26	± 0.08	6000	5876	0
*For leng	*For lengths / stroke over the stated value in the table above please contact us.																
Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used). Operating Conditions																	
**For mi	nimum stro	ke belo	w the sta	ated valu	ue in the	table ab	ove plea	ise cont	act us.					Op	erating temp	. 0°C	C ~ +60°C
												Z		Du	ity cycle		100%
i Re All the capacit	Recommended values of loads Fpz Cz, C C Mz, Mpz Mz, Mpz Mz, Mpz Mz, Mpz Mz, Mpz																
theoret factor. applica recomr	capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)																
Modulu	Modulus of elasticity:																
E = 700	000 N / m	m²					F	S.	-			μ γ	Fpy 🕨 Cy, C				

General Technical Data for Double Carriage

Linear	Carriage	Dyna	amic load ca	apacity	*	Dynamic momen	ment *			Max. permissible loads			
Unit	Version							For	rces	Moments			
		C[N]	Cy [N]	Cz [N]	Mx[Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	
BR-S 40	2	9220	/	/	57	4.6 × A	$4.6 \times A$	7690	7690	28	3.8 × A	3.8 × A	
BT-S 40	2	/	6800	3400	40	1.7 × A	$3.4 \times A$	2030	2180	26	1.1 × A	1.0 × A	
V													

*A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated using our sizing selection tool on Unimotion web site.



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	**No loa	d torque	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring	* Max. acceleration
		Ma	With strip	Without strip						Cspec	
	[m / s]	[Nm]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BR-S 40	6	3.7	0.4 imes nc	$0.2 \times nc$	99	31 51	ΔT 3	20	235	225000	70
BT-S 40	10		$0.4 \times nc$	$0.2 \times nc$	55	51.01	A 3	20	200	223000	70

*Max. travel speed and max. acceleration of Linear unit with the Corrosion-resistant protection strip is 1.5 m/s and 50 m/s, respectively. For travel speed and acceleration over the stated value in the table above please contact us.

*The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation. nc - Number of carriages

Mass and mass moment of inertia

Linear Unit	* Mass of linear unit	* Mass moment of inertia	Planar m ine	oment of rtia
	[kg]	[10 ⁻⁵ kg m²]	ly [cm ⁴]	lz [cm ⁴]
BR-S 40	$1.3 + 0,0024 \times (Abs. stroke + (nc - 1) \times A) + 0.28 \times (nc - 1)$	$9.7 + 0,0035 \times (Abs. stroke + (nc - 1) \times A) + 7.0 \times (nc - 1)$	0.9	11.6
BT-S 40	$1.25 + 0,0022 \times (Abs. stroke + (nc - 1) \times A) + 0.26 \times (nc - 1)$	$9.3 + 0,0035 \times (Abs. stroke + (nc - 1) \times A) + 6.5 \times (nc - 1)$	9.0	11.0
*	- []			

^{*}Absolute stroke [mm] A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

i

Deflection of the linear unit





Linear Unit doesn't include any safety stroke. Absolute stroke = Effective stroke + 2 x Safety stroke



i Lifetime lubrication



TYPE 0



TYPE 1 L and 1 R

TYPE 2







L = Effective stroke + 2 × Safety stroke + Lv + A × (nc - 1) + 32 mm

Ltotal = L + 135 mm

A ≥ Lv + 24 mm !

401.5

Alim

General technical data

Linear Unit	near Carriage i Dynamic Jnit length load capacity			Dynamic Ma moment Forces				Max. rces	lax. permissible loads Moments		nts	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	<mark>米米</mark> Min. stroke	
	Lv [mm]	C [N]	Cy [N]	Cz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-S 65 S	140	9900	/	/	79	59	59	3270	5100	34	34	34	1.00	± 0.08		5820	40
BR-S 65 L	190	19800	/	/	158	1025	1025	6540	10190	60	530	340	1.45	± 0.08	6000	5770	40
BT-S 65 L	190	/	8600	4400	74	186	425	1920	1470	25	62	95	1.31	± 0.08		5770	0
* For leng Values fo particular	* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).																
** For mi	particular size of the linear unit needs to be used). ** For minimum stroke below the stated value in the table above please contact us. Operating conditions Operating temp. 0°C ~ +60°C																
i R	ecomme	nded	values	ofloa	ads						Z			D	uty cycle		100%
All the capacit theoret factor. applica recomm	i Recommended values of loads All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)																
Moduli	lodulus of elasticity:																

Fpy Cy, C

 $E = 70000 \text{ N} / \text{mm}^2$

General technical data for double carriage

Linear	Carriage	Dyna	amic load ca	apacity	*	Dynamic momen	t	*		Max. permi	ssible loads	
Unit	VEISIOIT							For	rces		Moments	
		C[N]	Cy [N]	Cz [N]	Mx[Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]
BR-S 65	S2	19800	/	/	158	9.9 × A	9.9 imes A	6540	10190	68	5.1 × A	3.3 × A
BR-S 65	L2	39600	/	/	316	19.8 × A	19.8 × A	13080	20380	120	10.2 × A	$6.5 \times A$
BT-S 65	L2	/	17200	8800	148	$4.4 \times A$	$8.6 \times A$	3850	2940	50	1.5 × A	1.9 × A

*A - Distance between carriages [mm]. More info on following pages.





Drive and belt data

Linear Unit	* Max. travel speed [m / s]	Max. drive torque Ma [Nm]	** No Io ^{With} strip	oad ^{Without} strip	Puley drive ratio [mm / rev]	Pulley diameter [mm]	Belt type	Belt width	Max. force transmited by belt	Specific spring Cspec [N]	* Max. acceleration [m/s ²]
BR-S 65 S			1.1 × nc	0.8 × nc							
BR-S 65 L	6	13.1	1.2 × nc	0.9 × nc	165	52.52	AT 5	32	500	600000	70
BT-S 65 L	10		1.0 × nc	0.7 × nc							

* Max. travel speed and max. acceleration of Linear unit with the Corrosion-resistant protection strip is 1,5 m/s and 50 m/s, respectively. For travel speed and acceleration over the stated value in the table above please contact us.

* The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages

Mass and mass moment of inertia

Linear Unit	* Mass of linear unit	* Mass moment of inertia	Planar m ine	oment of rtia
	[kg]	[10 ⁻⁵ kg m ²]	ly [cm ⁴]	lz [cm ⁴]
BR-S 65 S	4,0 + 0.0055 × (Abs. stroke + (nc - 1) × A) + 1.00 × (nc - 1)	98.4 + 0.0154 × (Abs. stroke + (nc - 1) × A) + 69.0 × (nc - 1)		
BR-S 65 L	4,6 + 0.,0055 × (Abs. stroke + (nc - 1) × A) + 1.45 × (nc - 1)	130.1 + 0.0154 × (Abs. stroke + (nc - 1) × A) + 100.0 × (nc - 1)	59.7	74.4
BT-S 65 L	4,3 + 0.0047 \times (Abs. stroke + (nc - 1) \times A) + 1.31 \times (nc - 1)	120.4 + 0.0154 × (Abs. stroke + (nc - 1) × A) + 90.3 × (nc - 1)		
* Absolute strok A - Distance be	e [mm] tween carriages [mm]. More info on following pages.	Mass calculation motor, reduction	n doesn´t include n gear, switches	e mass of and clamps.

A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages

Deflection of the linear unit



Unsupported profile length Lp [mm]

Unsupported profile length Lp [mm]





50 85 M6x1 - 6H 8 mm deep i Journal with or without Keyway. Ð S 64 ŀ 33 5 P9/h9 DIN 6885 A Ø16 h7



In order to improve the products in this catalog the specifications are subject to change without notice.

Ø42 H7

1.6 mm deep



General technical data

Linear Unit	Carriage Iength	Dynamic load capacity Dynamic moment C Cy Cz Mx My My						For	Max. p rces	permissit	ole loads Momer	nts	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	** Min. stroke
	Lv [mm]	C [N]	Cy [N]	Cz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-S 80 S	170	17100	/	/	185	130	130	4470	7530	110	122	100	1.72	± 0.08		5788	55
BR-S 80 L	260	34200	/	/	370	2565	2565	8930	15060	150	1130	670	2.72	± 0.08	6000	5698	55
BT-S 80 L	260	/	17100	9000	198	511	1145	3400	1760	39	101	228	2.73	± 0.08		5698	0
* For len Values f (equatic ** For m I R All the capacit theoref factor. applica recom Modull E = 700	gths / stroke or max. stro on of definir inimum stro ecomme cies state cical with The safe tion and mend a r us of elas	a over the bke are in ong the lin bke belo nded d in the out co ty fact its reen inimits sticity	e stated not valid near unit w the sta values values ic mor ponside or dep queste um saf	value ir for mul length atted val of loa ments er tab ing au bends d safe rety fa	n the tab tiple carri- for partic ue in the ads and lo le are on the ety. We ctor (fs	le above riages cular size table ab pad ety s =5.0)	please of the I ove plea	contact inear ui asse con	us. hit needs tact us.	Mx, M	Fpz	Mz, Mp	My, M Fpy Cy, C	Op Du For pres	erating condi erating temp. ty cycle operating tem ented range,	tions 0°C	- +60°C 100% but of the stact us.

General technical data for double carriage

Linear	Carriage	Dyna	amic load ca	apacity	*	Dynamic momen	t	*		Max. perm	issible loads	
Unit	Version							For	rces		Moments	
		C[N]	Cy [N]	Cz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]
BR-S 80	S2	34200	/	/	370	17.1 × A	17.1 × A	8930	15060	220	7.5 × A	4.5 imes A
BR-S 80	L2	68400	/	/	740	34.2 × A	34.2 × A	17860	30130	300	15.1 × A	8.9 × A
BT-S 80	L2	/	34200	18000	396	9.0 × A	17.1 × A	6800	3530	78	1.8 × A	$3.4 \times A$
×											110 / / / /	

*A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated by contacting our engineers.



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque Ma	** No I tore ^{With} ^{strip}	oad que ^{Without} strip	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant Cspec	* Max. acceleration
	[m/s]	[Nm]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BR-S 80 S	0		1.5 × nc	1.2 × nc							
BR-S 80 L	6	29.4	1.7 × nc	1.4 × nc	210	66.84	AT 5	50	880	960000	70
BT-S 80 L	10		$1.4 \times nc$	1.1 × nc							

* Max. travel speed and max. acceleration of Linear unit with the Corrosion-resistant protection strip is 1,5 m/s and 50 m/s, respectively. For travel speed and acceleration over the stated value in the table above please contact us.

* The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages

Mass and mass moment of inertia

Linear Unit	* Mass of linear unit	* Mass moment of inertia	Planar m ine	oment of rtia
	[kg]	[10 ⁻⁵ kg m ²]	ly [cm ⁴]	lz [cm ⁴]
BR-S 80 S	$6.8 + 0.0085 \times (Abs. stroke + (nc - 1) \times A) + 1.72 \times (nc - 1)$	310.,6 + 0.0391 × (Abs. stroke + (nc - 1) × A) + 192.1 × (nc - 1)		
BR-S 80 L	8.4 + 0.0085 × (Abs. stroke + (nc - 1) × A) + 2.72 × (nc - 1)	423.3 + 0.0391 × (Abs. stroke + (nc - 1) × A) + 303.,8 × (nc - 1)	129.1	173.4
BT-S 80 L	8.2 + 0.0075 × (Abs. stroke + (nc - 1) × A) + 2.73 × (nc - 1)	424.4 + 0.0391 × (Abs. stroke + (nc - 1) × A) + 304.9 × (nc - 1)		
* Absolute strok	e [mm]	Mass calculation	n doesn't include	mass of
A - Distance bet	ween carriages [mm]. More info on following pages.	1 motor, reduction	n gear, switches	and clamps.

A - Distance between carriages [mm]. More info on following pages.

nc - Number of carriages

Deflection of the linear unit



In order to improve the products in this catalog the specifications are subject to change without notice.



In order to improve the products in this catalog the specifications are subject to change without notice.



General technical data

Linear Unit	Carriage length	i Ioi	Dynamic ad capac	c iity	1 Dynamic moment Mx My Mz			For	Max. p rces	permissit	ole loads Momer	nts	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	X X Min. stroke
	Lv [mm]	C [N]	Cy [N]	Cz [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	L _{max} [mm]	[mm]	[mm]
BR-S 110 S	240	24800	/	/	315	220	220	5000	10130	135	180	100	3.25	± 0.08		5748	65
BR-S 110 L	330	49600	/	/	630	3840	3840	10000	20260	295	1570	775	4.61	± 0.08	6000	5658	65
BT-S 110 L	330	/	31000	14000	406	877	2325	6200	3410	99	214	465	4.78	± 0.08		5658	0
* For leng	gths / stroke	e over th	e stated	value ir	n the tab	e above	please	contact	us.								
Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).														itions			
**For mi	nimum stro	oke belo	w the sta	ated valu	ue in the	table ab	ove plea	ase cont	tact us.					O	perating temp	. 0°C	~ +60°C
Duty cycle															100%		
All the capacit theoret factor.	**For minimum stroke below the stated value in the table above please contact us. **For minimum stroke below the stated value in the table above please contact us. **The commended values of loads All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs = 5.0).																
Moduli	Modulus of elasticity :																
E = 700	E = 70000 N / mm																

General technical data for double carriage

Linear	Carriage	Dyna	imic load ca	apacity	*	Dynamic momen	t	*		Max. permi	ssible loads	
Unit	version					1 1		For	rces		Moments	
		C[N]	Cy [N]	Cz [N]	Mx[Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy[Nm]	Mpz [Nm]
BR-S 110	S2	49600	/	/	630	24.8 × A	24.8 × A	10000	20260	270	10.1 × A	5.0 × A
BR-S 110	L2	99200	/	/	1260	49.6 × A	49.6 × A	20000	40520	590	20.3 × A	10.0 × A
BT-S 110	L2	/	62000	28000	812	14.0 × A	31.0 × A	12400	6830	198	$3.4 \times A$	6.2 × A

* A - Distance between carriages [mm]. More info on following pages.



Presented values are for informational purposes only. Exact values can be provided by contacting our sales engineers.



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque Ma	** No load torque ^{With} Without strip		Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant Cspec	* Max. acceleration
	[m / s]	[Nm]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BT-S 110 L	10	68.5	$2.2 \times nc$	2.0 × nc							
BR-S 110 S	6	with Keyway 2 82.6	$2.2 \times nc$	2.0 × nc	c 300	95.49	AT 10	50	1730	2145000	70
BR-S 110 L	0	without Keyway	$2.7 \times nc$	2.3 × nc							

* Max. travel speed and max. acceleration of Linear unit with the Corrosion-resistant protection strip is 1,5 m/s and 50 m/s, respectively.

For travel speed and acceleration over the stated value in the table above please contact us.

* The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation. nc - Number of carriages

Mass and mass moment of inertia

1

Linear Unit	* Mass of linear unit	* Mass moment of inertia	Planar m ine	oment of rtia
	[kg]	[10 ⁻⁵ kg m ²]	ly [cm ⁴]	lz [cm ⁴]
BR-S 110 S	15.0 + 0.015 \times (Abs. stroke + (nc - 1) \times A) + 3.25 \times (nc - 1)	1065.0 + 0.137 × (Abs. stroke + (nc - 1) × A) + 741.9 × (nc - 1)		
BR-S 110 L	17.7 + 0.015 × (Abs. stroke + (nc - 1) × A) + 4.61 × (nc - 1)	1381.0 + 0.137 × (Abs. stroke + (nc - 1) × A) + 1050.9 × (nc - 1)	513.0	620.0
BT-S 110 L	16.3 + 0.0133 × (Abs. stroke + (nc - 1) × A) + 4.78 × (nc - 1)	1420.0 + 0.137 \times (Abs. stroke + (nc - 1) \times A) + 1089.6 \times (nc - 1)		
* Absolute strok	e [mm]		doesn't include	mass of

A - Distance between carriages [mm]. More info on following pages.

nc - Number of carriages

Deflection of the linear unit

motor, reduction gear, switches and clamps.



-BR-S 110-





In order to improve the products in this catalog the specifications are subject to change without notice.



In order to improve the products in this catalog the specifications are subject to change without notice.





nc - Number of carriages

CHARACTERISTICS

The SR-S series describes Linear Units with precision ball screw drive, integrated guide rail and compact dimensions. They provide high performances features, such as high speeds, good accuracy and repeatability. They can easily be combined to multi-axis systems. Excellent price-/performance ratio and quick delivery time are ensured.

The compact, precision-extruded aluminum Profile from 6063 AL with integrated Zero-backlash Ball rail guide system, allows high load capacities and optimal cycles for the movement of larger masses at high speed.

In the Linear Units SR-S a precision ball screw, with tolerance class ISO7 (ISO5 on request), with reduced backlash of the ball nut is used.

A corrosion-resistant protection strip, protects all the parts in the profile from dust and other contaminants.

The aluminum profile includes T-slots for fixing the Linear Unit and for attaching sensors and switches. Also, a Reed switch can be used here. The carriage, with central lubrication port, allows easy central re-lubrication of ball screw and Ball rail guide and provides the possibility to attach additional accessories on the side. For the Linear Units SR-S various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.

To achieve higher speeds at the same stroke of the linear unit, the ball screw support system can be integrated. With this feature vibrations and deflections of the ball screw are reduced, therefore longer strokes are possible. The linear unit with integrated support system can have a higher axial load capacity.

Ball screw supports are made out of high quality plastic materials with high wear resistance properties. Our system enables ball screw support in horizontal or vertical positioning of the linear unit.

A 2LR version of SR-S linear unit is available, where two carriages are moving simultaneously in opposite directions. Both right and left handed precision ball screws are used, which are rigidly connected. The ball screw support system can also be integrated.



i The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0.35 mm/m; Max. torsion = 0.35 mm/m; Angular torsion = 0.2 mm/40 mm; Parallelism = 0.2 mm

STRUCTURAL DESIGN

Standard version



- 1 Drive block with floating bearing (SR-S 110 fixed bearing)
- 2 Corrosion-resistant protection strip3 Ball screw tolerance ISO7 (ISO5 available on request)
- 4 Carriage; with built in Magnets
- 5 Aluminium profile-Hard anodized
- 6 Integrated Linear Ball Guideway
- 7 Central lubrication port; both sides
- 8 End block with fixed bearing (SR-S 110 floating bearing)
- 9 Screw support SA



2LR version

- 1 Carriage; with build in right hand ball nut
- 2 Right hand ball screw
- 3 Carriage; with build in left hand ball nut
- 4 Left hand ball screw
- 5 Central screw support fixed
- 6 Screw support SA

HOW TO ORDER

	SR	0110	S - 5	850 -	32	7	1 - W	A
Series Prefix:								
Size:								
65: 0065 80: 0080 110: 0110								
Series Suffix:S								
Absolute stroke [mm]: (Absolute stroke = Effective stroke + 2 >	c Safety str	oke)						
Ball Screw Dia./Pitch: SR0040 (⊘ 12): 05, 10 SR0065 (⊘ 16): 05, 10, 16 SR0080 (⊘ 20): 05, 10, 20, 50 SR0110 (⊘ 32): 05, 10, 20, 32								
Ball Screw Tolerance: 7: ISO7 5: ISO5								
Ball Screw Journal: 0: Without Keyway 1: With Keyway								
Number of Screw Supports n _{SA} :	SR0065, a r	max. of 4SA	is available).				
Version: A: Both right and left screws are used, s B: Standard version, single carriage Available for SR0065: 16x5, 16x10 SR0080: 20x5	single carr	iage						
C: Both right and left screws are used, I	multi-carria	age						

D: Standard version, multi-carriage

Available for SR0065: 16x5, 16x10

SR0080: 20x5

S: Special Version

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i	i Dynamic moment			Max. permissible loads Forces Moments			Moved mass	Max. Repeatability	* Max. length	* Max. stroke	** Min. stroke	
	Lv [mm]	C[N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
SR-S 40 S	132	9900	79	59	59	3270	5100	34	34	34	0.45	± 0.1	5000	5813	40
SR-S 40 L	200	19800	158	660	660	6540	10190	60	341	219	0.72	± 0.1	5960	5745	40
* For lengths Values for ma linear unit ne	 * For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used). 														
* For minimum stroke below the stated value in the table above please contact us.						Op	erating tem	np. 0'	°C ~ +60°C						
2						Du	ty cycle		100%						

Fpz, C

Mx.

For operating temperature out of the presented range, please contact us.

Recommended values of loads All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safet factor. The safety factor depends on the application and its requested safety.

We recommend a minimum safety factor

Modulus of elasticity

 $E = 70000 \text{ N} / \text{mm}^2$

General technical data for double carriage

Linear Unit	Carriage	Dynamic	*	Dynamic moment			* Max. permissible loads					
	version	C [N]					Forces Moments					
			Mx [Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]		
00.0	S2	19800	158	9.9 × A	9.9 imes A	6540	10190	68	5.1 × A	3.3 × A		
SK-5 40	L2	39600	317	19.8 × A	19.8 × A	13080	20380	120	10.2 × A	6.5 × A		

* A - Distance between carriages [mm]. More on page 4.030.0

Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Drive and belt data

i

Linear Unit	**Max. travel speed [m / s]	Max. drive torque [Nm]	* No load torque [Nm]	Puley drive ratio [mm / rev]	Pulley diameter [mm]	Belt type	Belt width [mm]	Max. force transmited by belt [N]	Specific spring constant Cspec [N]	** Max. acceleration [m/s ²]
SR-S 40 S	2	7 5	$1.0 \times nc$	100	E7 01	ATE	10	262	225000	70
SR-S 40 L	3	7.5	1.1 × nc	180	57.31	AIS	12	202	235000	70

* The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages

**For travel speed and acceleration over the stated value in the table above please contact us.

Mass, moved mass, mass moment of inertia and no load torque

Linear Unit	Ball screw	Number of SA	* Mass of linear unit	* Moved mass
	[d×l]	n _{SA}	[kg]	[kg]
		0	$1.2 + 0.0028 \times (Abs. stroke + (nc - 1) \times A) + 0.47 \times (nc - 1)$	0.47 + 0.47 × (nc - 1)
	12 × 5	2	$1.3 + 0.0028 \times (Abs. stroke + (nc - 1) \times A) + 0.47 \times (nc - 1)$	0.50 + 0.47 × (nc - 1)
CD C 40		4	$1.4 + 0.0028 \times (Abs. stroke + (nc - 1) \times A) + 0.47 \times (nc - 1)$	0.53 + 0.47 × (nc - 1)
5R-5 40		0	$1.2 + 0.0028 \times (Abs. stroke + (nc - 1) \times A) + 0.47 \times (nc - 1)$	0.47 + 0.47 × (nc - 1)
	12 × 10	2	$1.3 + 0.0028 \times (Abs. stroke + (nc - 1) \times A) + 0.47 \times (nc - 1)$	0.50 + 0.47 × (nc - 1)
		4	1.4 + 0.0028 × (Abs. stroke + (nc - 1) × A) + 0.47 × (nc - 1)	0.53 + 0.47 × (nc - 1)

Linear Unit	Ball screw	Number of SA	* Mass moment of inertia	* No load torque **
	[d × l]	n _{SA}	[10 ^{.5} kg m ²]	[Nm]
		0	$0.48 + 0.0012 \times (Abs. stroke + (nc - 1) \times A) + 0.03 \times (nc - 1)$	0.08 + 0.08 × (nc - 1)
	12×5	2	$0.53 + 0.0012 \times (Abs. stroke + (nc - 1) \times A) + 0.03 \times (nc - 1)$	0.09 + 0.08 × (nc - 1)
SP S 40		4	$0.57 + 0.0012 \times (Abs. stroke + (nc - 1) \times A) + 0.03 \times (nc - 1)$	0.10 + 0.08 × (nc - 1)
511-5 40		0	$0.57 + 0.0012 \times (Abs. stroke + (nc - 1) \times A) + 0.12 \times (nc - 1)$	0.09 + 0.09 × (nc - 1)
	12 × 10	2	$0.62 + 0.0012 \times (Abs. stroke + (nc - 1) \times A) + 0.12 \times (nc - 1)$	0.11 + 0.09 × (nc - 1)
		4	$0.67 + 0.0012 \times (Abs. stroke + (nc - 1) \times A) + 0.12 \times (nc - 1)$	0.14 + 0.09 × (nc - 1)

i

clamps.

* Absolute stroke [mm] A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages

The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

Mass calculation doesn't include mass of motor, reduction gear, switches and





The maximum permissible deflection dmax must not be exceeded. In the case that maximum deflection d exceeds the maximum permissible deflection dmax additional profile supports are needed.





Deflection of the linear unit

1

DIMENSIONS

Linear Unit doesn't include any safety Absolute stroke = Effective stroke + 2 x Safety stroke.





Defining of the linear unit length

L = Effective stroke + 2 × Safety stroke + Lv + 2 × LSA + A × (nc - 1) + 10 mm

Ltotal = L + 45 mm, Lv = 150 mm



Multiple carriages





Maximum travel speed as a function of the profile length (Vmax - L curves)



General technical data

Linear Unit	Carriage length	i Dynamic Load capacity	i Dynamic moment			Max. permissible loads Forces Moments					* Max. length	* Max. stroke
	Lv [mm]	C[N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fру [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	Lmax [mm]	[mm]
SR-S 65	220	19800	158	700	700	6540	10190	94	350	233	2920	2690
SR-S 65 2LR	220	19800	158	700	700	6540	10190	94	350	233	5789	2667

* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages and screw support SA (equation of defining the linear unit length for particular size of the linear unit needs to be used). Operating conditions

i Recommended values of loads:

 Operating conditions

 Operating temp.
 0°C ~ +60°C

 Duty cycle
 100%

For operating temperature out of the

presented range, please contact us

All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)



General technical data for double carriage

Linear Unit	Number of	Dynamic	* Dynamic moment			*	Ma	x. permissible	ssible loads		
	carriages	гоад сарасну				For	ces		Moments		
		C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	
SR-S 65 / SR-S 65 2LR	2	39600	316	19.8 × A	19.8 × A	13070	20380	188	10.2 × A	$6.5 \times A$	
* A - Distance between	* A - Distance between carriages [mm]. More info on following pages.										
Presented values are for informational purposes only. Exact values can be calculated using our sizing selection tool on Unimotion web site.											

Ball Screw Drive data

Linear Unit	Ball screw	³ Max. rotational (Without SA)	¹ Max. (Without SA)	Lead constant	² Max. Rep prec [m	eatability ision m]	Dynamic load capacity BS	⁵ Max. axial load	Max. drive torque	⁴ Min. stroke	¹ Max. acceleration
	[d×l]	[rev / min]	[m / s]	[mm / rev]	ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]
	16 × 5		0.35	5	± 0.02	± 0.01	13150	8700	5.5 with Keyway 7.7 without Keyway		
SR-S 65 SR-S 65 2LR	16 × 10	4200	0.70	10	± 0.02	± 0.01	11550	6730	5.5 with Keyway	40	20
	16 × 16		1.12	16	± 0.02	± 0.01	8170	4200	11.9 without Keyway		

¹ Max. travel speed depends of the length of the linear unit, see diagram for particular size of the linear unit.

For travel speed and acceleration over the stated value in the table above or diagrams please contact us.

 2 For the ball nut with the preload of 2%, please contact us.

³ With SA or 2LR version the max. rotation speed is limited to 3000 rev / min.

 $^{\rm 4}$ For minimum stroke below the stated value in the table above please contact us.

⁵ In the case of 2RL version the axial load is total axial load of both carriages.

Mass, moved mass, mass moment of inertia and no load torque

Linear Unit	Ball screw	Number of SA	* Mass of linear unit	* Moved mass
	[d × l]	n _{SA}	[kg]	[kg]
		0	4.0 + 0.0073 × (Abs. stroke + (nc - 1) × A) + 1.5 × (nc - 1)	1.50 + 1.50 × (nc - 1)
	16 × 5	2	4.5 + 0.0073 \times (Abs. stroke + (nc - 1) \times A) + 1.5 \times (nc - 1)	1.58 + 1.50 × (nc- 1)
		4	$5.0 + 0.0073 \times (Abs. stroke + (nc - 1) \times A) + 1.5 \times (nc - 1)$	1.66 + 1.50 × (nc - 1)
		0	7.2 + 0.0146 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)	3.00 + 3.00 × (nc - 1)
	16 × 5 2LR version	2	$8.2 + 0.0146 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)$	3.16 + 3.00 × (nc - 1)
		4	9.2 + 0.0146 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)	3.32 + 3.00 × (nc - 1)
		0	4.0 + 0.0073 × (Abs. stroke + (nc - 1) × A) + 1.5 × (nc - 1)	1.50 + 1.50 × (nc - 1)
SR-S	16 × 10	2	4.5 + 0.0073 × (Abs. stroke + (nc - 1) × A) + 1.5 × (nc - 1)	1.58 + 1.50 × (nc - 1)
65		4	5.0 + 0.0073 \times (Abs. stroke + (nc - 1) \times A) + 1.5 \times (nc - 1)	1.66 + 1.50 × (nc - 1)
		0	7.2 + 0.0146 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)	3.00 + 3.00 × (nc - 1)
	16 × 10 2LB version	2	$8.2 + 0.0146 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)$	3.16 + 3.00 × (nc - 1)
		4	9.2 + 0.0146 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)	3.32 + 3.00 × (nc - 1)
		0	4.0 + 0.0073 × (Abs. stroke + (nc - 1) × A) + 1.5 × (nc - 1)	1.50 + 1.50 × (nc - 1)
	16 × 16	2	4.5 + 0.0073 \times (Abs. stroke + (nc - 1) \times A) + 1.5 \times (nc - 1)	1.58 + 1.50 × (nc - 1)
		4	5.0 + 0.0073 × (Abs. stroke + (nc - 1) × A) + 1.5 × (nc - 1)	1.66 + 1.50 × (nc - 1)

Linear Unit	Ball screw	Number of SA	* Mass moment of inertia	* ** No load torque
	[d × l]	n _{SA}	[10 ⁵ kg m ²]	[Nm]
		0	$1.6 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.09 \times (nc - 1)$	0.14 + 0.14 × (nc - 1)
	16 × 5	2	$1.9 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.09 \times (nc - 1)$	0.16 + 0.14 × (nc - 1)
		4	$2.2 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.09 \times (nc - 1)$	0.18 + 0.14 × (nc - 1)
	10 5	0	$2.9 + 0.0104 \times (Abs. stroke + (nc - 1) \times A) + 0.19 \times (nc - 1)$	0.28 + 0.28 × (nc - 1)
	2LR version	2	$3.5 + 0.0104 \times (Abs. stroke + (nc - 1) \times A) + 0.19 \times (nc - 1)$	0.32 + 0.28 × (nc - 1)
		4	$4.1 + 0.0104 \times (Abs. stroke + (nc - 1) \times A) + 0.19 \times (nc - 1)$	0.35 + 0.28 × (nc - 1)
		0	$1.9 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.15 + 0.15 × (nc - 1)
SR-S	16 × 10	2	$2.2 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.19 + 0.15 × (nc - 1)
60		4	$2.5 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.22 + 0.15 × (nc - 1)
		0	$3.5 + 0.0104 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.30 + 0.30 × (nc - 1)
	16 × 10 2LR version	2	$4.1 + 0.0104 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.34 + 0.30 × (nc - 1)
		4	$4.8 + 0.0104 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.37 + 0.30 × (nc - 1)
		0	$2.5 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.97 \times (nc - 1)$	0.20 + 0.20 × (nc - 1)
	16 × 16	2	$2.8 + 0.0052 \times (Abs. stroke + (nc - 1) \times A) + 0.97 \times (nc - 1)$	0.26 + 0.20 × (nc - 1)
		4	3.2 + 0.0052 × (Abs. stroke + (nc - 1) × A) + 0.97 × (nc - 1)	0.31 + 0.20 × (nc - 1)

* Absolute stroke [mm]

A - Distance between carriages [mm]. More info on following pages.

1 Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

nc - Number of carriages

* The stated values are for strokes (and for distances between the carriages A) up to 500mm No Load Torque value increases with stroke (and with A) elongation.

Planar moment of inertia

Linear Unit	Planar moment of inertia			
	ly [cm ⁴]	lz [cm ⁴]		
SR-S 65 SR-S 65 2LR	71.3	89.4		

Deflection of the linear unit



Unsupported profile length Lp [mm]



Maximum travel speed as a function of the profile length (Vmax - L curves)



SR-S 65 —

Deflection of the 2LR version



SR-S 65 2LR



Maximum travel speed as a function of the profile length (Vmax - L curves)

SR-S 65 2LR -



 \star Max. length Lmax of SR-S 65 2LR linear unit with 16x10 ball screw.

Linear Unit doesn't include any safety Absolute stroke = Effective stroke + 2 x Safety stroke stroke.



2LR version



n	L_SA	L_{2LR}
0	5.0	5.0
2SA	31.0	67.0
4SA	62.0	129.0

L_{SA} Additional length [mm]

 $L_{\rm 2LR}\,$ Min. distance between carriages [mm]


Defining of the linear unit length

i Standard version

i Version 2LR

 $\label{eq:L} L = Effective stroke + 2 \times Safety stroke + Lv + 2 \times LSA + A \times (nc - 1)$ Ltotal = L + 48 mm, Lv = 220 mm



Multiple carriages

A ≥ Lv Connection between the carriages must be provided by the customer nc - Number of carriages $L=2\times (Effective stroke + 2\times Safety stroke) + 2\times Lv + 2\times LSA + L2LR + A\times (nc - 1)$ Ltotal = L + 48 mm, Lv = 220 mm



right side (ii)

Multiple carriages

 $A \ge Lv$ (Connection between the carriages must be provided by the customer

nc - Number of carriages

General technical data

Linear Unit	Carriage length	i Dynamic Load capacity	j Dynamic moment			Max. permissible loads Forces Moments					* Max. length	* Max. stroke
	Lv [mm]	C[N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fру [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	Lmax [mm]	[mm]
SR-S 80	290	34200	370	1470	1470	8930	15070	150	500	384	5480	5163
SR-S 80 2LR	290	34200	370	1470	1470	8930	15070	150	500	384	11055	5224

* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages and screw support SA (equation of defining the linear unit length for particular size of the linear unit needs to be used).

i Recommended values of loads:

All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)



General technical data for double carriage

Linear Unit	Number of	Dynamic	*	Dynamic mon	nent	*	Ma	x. permissible	ssible loads		
	carriages	Load capacity				Forces		Moments			
		C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fру [N]	Fpz [N]	Mpx [Nm]	M _{PY} [Nm]	Mpz [Nm]	
SR-S 80 / SR-S 80 2LR	2	68400	740	$34.2 \times A$	34.2 × A	17860	30130	300	15.0 × A	8.9 × A	

* A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated using our sizing selection tool on Unimotion web site.



Operating temp.

For operating temperature out of the

presented range, please contact us

Duty cycle

0°C ~ +60°C

100%

Ball Screw Drive data

i

Linear Unit	Ball screw	³ Max. rotational	¹ Max.	Lead constant	² Max. Repeatability precision [mm]		Dynamic load capacity BS	⁵ Max. axial Ioad	Max. drive torque	⁴ Min. stroke	¹ Max. acceleration
	[d × l]	(Without SA) [rev / min]	(Without SA) [m / s]	[mm / rev]	standard ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]
SR-S 80 SR-S 80 2LR	20 × 5	3300	0.28	5	± 0.02	± 0.01	14800	14800	11.9 with Keyway 13.0 without Keyway		
	20 × 10		3300	0.55	10	± 0.02	± 0.01	15900	13850	11.9	55
	20 imes 20		1.10	20	± 0.02	± 0.01	16250	6930	with Keyway 24.5		
	20 imes 50	3000	2.50	50	± 0.02	± 0.01	13000	2770	without Keyway		

¹ Max. travel speed depends of the length of the linear unit, see diagram for particular size of the linear unit. For travel speed and acceleration over the stated value in the table above or diagrams please contact us.

² For the ball nut with the preload of 2%, please contact us.

 3 With SA or 2LR version the max. rotation speed is limited to 3000 $\mbox{rev}\,/\,\mbox{min}.$

⁴ For minimum stroke below the stated value in the table above please contact us.

⁵ In the case of 2RL version the axial load is total axial load of both carriages.

Mass, moved mass, mass moment of inertia and no load torque

Linear Unit	Ball screw	Number of SA	* Mass of linear unit	* Moved mass
	[d × l]	n _{SA}	[kg]	[kg]
	20 × 5	0	$8.2 + 0.0114 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)$	3.00 + 3.00 × (nc - 1)
		2	8.9 + 0.0144 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.07 + 3.00 × (nc- 1)
		4 / 6 / 8 / 10	9.7 + 0.4* (n _{SA} -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.21 + 0.035* (n _{SA} -4) + 3.00 × (nc - 1)
		0	$14.6 + 0.0228 \times (Abs. stroke + (nc - 1) \times A) + 6.0 \times (nc - 1)$	6.00 + 6.00 × (nc - 1)
	20 × 5 2LR version	2	$15.9 + 0.0228 \times (Abs. stroke + (nc - 1) \times A) + 6.0 \times (nc - 1)$	6.14 + 6.00 × (nc - 1)
		4 / 6 / 8 / 10	17.5 + 0.8* (n_{SA} -4) + 0.0228 × (Abs. stroke + (nc - 1) × A) + 6.0 × (nc - 1)	$6.42 + 0.07* (n_{SA} - 4) + 6.00 \times (nc - 1)$
		0	8.2 + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.00 + 3.00 × (nc - 1)
SR-S	20 × 10	2	8.9 + 0.0144 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.07 + 3.00 × (nc - 1)
80		4 / 6 / 8 / 10	9.7 + 0.4* (n _{SA} -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.21 + 0.035* (n _{SA} -4) + 3.00 × (nc - 1)
		0	8.2 + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.00 + 3.00 × (nc - 1)
	20 × 20	2	8.9 + 0.0144 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.07 + 3.00 × (nc - 1)
		4 / 6 / 8 / 10	9.7 + 0.4* (n _{SA} -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	$3.21 + 0.035^* (n_{SA} - 4) + 3.00 \times (nc - 1)$
		0	8.2 + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.00 + 3.00 × (nc - 1)
	20 × 50	2	8.9 + 0.0144 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.07 + 3.00 × (nc - 1)
		4/6/8/10	9.7 + 0.4* (n _{SA} -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	$3.21 + 0.035^* (n_{SA} - 4) + 3.00 \times (nc - 1)$

Linear Unit	Ball screw	Number of SA	* Mass moment of inertia	* No load torque
	[d × l]	n _{SA}	[10 ⁵ kg m ²]	[Nm]
		0	5.6 + 0.0127 × (Abs. stroke + (nc - 1) × A) + 0.19 × (nc - 1)	0.23 + 0.23 × (nc - 1)
	20 × 5	2	$6.2 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.19 \times (nc - 1)$	0.26 + 0.23 × (nc - 1)
		4 / 6 / 8 / 10	7.0 + 0.4* (n _{SA} -4) + 0.0127 × (Abs. stroke + (nc - 1) × A) + 0.19 × (nc - 1)	$0.31 + 0.015^* (n_{SA} - 4) + .23 \times (nc - 1)$
	00 F	0	$9.5 + 0.0254 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.468 + 0.46 × (nc - 1)
	20 × 5 2LR version	2	$10.7 + 0.0254 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.51 + 0.46 × (nc - 1)
		4 / 6 / 8 / 10	12.3 + 0.8* (n _{SA} -4) + 0.0254 × (Abs. stroke + (nc - 1) × A) + 0.38 × (nc - 1)	$0.62 + 0.03* (n_{SA} - 4) + 0.46 \times (nc - 1)$
		0	$6.2 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.25 + 0.25 × (nc - 1)
SR-S	20 × 10	2	$6.8 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.30 + 0.25 × (nc - 1)
80		4 / 6 / 8 / 10	7.6 + 0.4* (n _{SA} -4) + 0.0127 × (Abs. stroke + (nc - 1) × A) + 0.76 × (nc - 1)	$0.41 + 0.025^* (n_{SA} - 4) + 0.25 \times (nc - 1)$
		0	$8.5 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 3.04 \times (nc - 1)$	0.30 + 0.30 × (nc - 1)
	20 × 20	2	$9.1 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 3.04 \times (nc - 1)$	0.41 + 0.30 × (nc - 1)
		4 / 6 / 8 / 10	10.1 + 0.5* (n _{SA} -4) + 0.0127 × (Abs. stroke + (nc - 1) × A) + 3.04 × (nc - 1)	$0.62 + 0.055^* (n_{SA} - 4) + 0.30 \times (nc - 1)$
		0	24.4 + 0.0127 × (Abs. stroke + (nc - 1) × A) + 19.00 × (nc - 1)	0.70 + 0.20 × (nc - 1)
	20 × 50	2	25.5 + 0.0127 × (Abs. stroke + (nc - 1) × A) + 19.00 × (nc - 1)	0.97 + 0.20 × (nc - 1)
		4/6/8/10	27.1 + 0.6* × (Abs. stroke + (nc - 1) × A) + 19.00 × (nc - 1)	1.50 + 0.135* (n _{SA} -4) + 0.70 × (nc - 1)

* Absolute stroke [mm]

A - Distance between carriages [mm]. More info on following pages.

i Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

nc - Number of carriages

** The stated values are for strokes (and for distances between the carriages A) up to 500mm No Load Torque value increases with stroke (and with A) elongation.

Planar moment of inertia

Linear Unit	Planar m ine	oment of rtia
	ly [cm ⁴]	lz [cm ⁴]
SR-S 80 SR-S 80 2LR	144.1	192.3

Deflection of the linear unit





Maximum travel speed as a function of the profile length (Vmax - L curves)



* Max. length Lmax of SR-S 80 linear unit with 20x10 ball screw.

Deflection of the 2LR version



SR-S 80 2LR -



Maximum travel speed as a function of the profile length (Vmax - L curves)

SR-S 80 2LR





1 Linear Unit doesn't include any safety Absolute stroke = Effective stroke + 2 x Safety stroke stroke.



2LR Version



 $L_{\,2LR}\,$ Min. distance between carriages $\,[$ mm]



Defining of the linear unit length

i Standard version

i 2LR version

L = Effective stroke + 2 × Safety stroke + Lv + 2 × LSA + A × (nc - 1) + 15 mm Ltotal = L + 81 mm, Lv = 290 mm



Right side (R)

Multiple carriages

A ≥ Lv (!) Connection between the carriages must be provided by the customer

nc - Number of carriages

 $L = 2 \times (Effective stroke + 2 \times Safety stroke) + 2 \times Lv + 2 \times LSA + L2LR + A \times (nc - 1) + 15 mm$ Ltotal = L + 81 mm, Lv = 290 mm



Multiple carriages

A≥Lv . Connection between the carriages must be provided by the customer

nc - Number of carriages

General technical data

Linear Unit	Carriage length	i Dynamic Load capacity	i Dy	i Dynamic moment			Max. ı ces	oermissib	le loads Moments	6	* Max. length	* Max. stroke
	Lv [mm]	C[N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	M _{px} [Nm]	M _{Py} [Nm]	Mpz [Nm]	Lmax [mm]	[mm]
SR-S 110	330	49600	630	2650	2650	10000	20260	295	670	535	5850	5456
* For lengths Values for ma length for par	* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages and screw support SA (equation of defining the linear unit length for particular size of the linear unit needs to be used).											
										Duty	/ cycle	100%
i Recor	nmended valu	ues of loads:				Z				_ Duty	, cycle	10070
All the dat stated in ti considerin depends of We recom Modulus of E = 70000	a of dynamic i he upper table g any safety f in the applicat mend a minim of elasticity N / mm ²	moments and lo are theoretical actor. The safety ion and its requ num safety facto	ad capaci without / factor ested safe or (fs =5.0)	ties ety.	Fr	DZ, C	Az, Mpz	Fpy,	c	presei	nted range, please	contact us.

General technical data for double carriage

Linear Unit	Number of	Dynamic Load capacity	*	Dynamic mor	* Max. permissible loads					
	Carriages	Luau capacity					ces	Moments		
		C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fру [N]	Fpz [N]	Mpx [Nm]	М _{ру} [Nm]	Mpz [Nm]
SR-S 110	2	99200	1260	49.6 × A	49.6 × A	20000	40500	590	20.3 × A	10.0 × A

 * A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated
 by contacting one of our sales engineers.

Ball Screw Drive data

Linear Unit	Ball screw	³ Max. rotational	¹ Max.	Lead constant	² Max. Repeatability precision [mm]		Dynamic load capacity BS	Max. axial Ioad	Max. drive torque	⁴ Min. stroke	¹ Max. acceleration
	[d × l]	[rev / min]	(Without SA) [m/s]	[mm / rev]	standard ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]
	32 × 5	2150	0.18	5	± 0.02	± 0.01	18850	18850	16.7 with Keyway 16.7 without Keyway	6E	
SR-S 110	32 × 10		0.50	10	± 0.02	± 0.01	37000	29600	27.3	05	20
	32 × 20	3000	1.00	20	± 0.02	± 0.01	22950	14800	with Keyway 52.3		
	32×32		1.60	32	± 0.02	± 0.01	15500	9240	without Keyway	70	

¹ Max. travel speed depends of the length of the linear unit, see diagram for particular size of the linear unit. For travel speed and acceleration over the stated value in the table above or diagrams please contact us.

² For the ball nut with the preload of 2%, please contact us.

3 With SA the max. rotation speed is limited to 3000 rev / min.

⁴ For minimum stroke below the stated value in the table above please contact us.

Planar moment of inertia

Linear Unit	Planar m ine	oment of rtia
	ly [cm ⁴]	lz [cm ⁴]
SR-S 110	562.0	669.0

Mass, moved mass, mass moment of inertia and no load torque

Linear Unit	Ball screw	Number of SA	* Mass of linear unit	* Moved mass
	[d×l]	n _{SA}	[kg]	[kg]
		0	$8.2 + 0.0114 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)$	3.00 + 3.00 × (nc - 1)
	20 × 5	2	8.9 + 0.0144 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.07 + 3.00 × (nc- 1)
		4 / 6 / 8 / 10	9.7 + 0.4* (n _{SA} -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	$3.21 + 0.035^* (n_{SA} - 4) + 3.00 \times (nc - 1)$
	00 F	0	$14.6 + 0.0228 \times (Abs. stroke + (nc - 1) \times A) + 6.0 \times (nc - 1)$	6.00 + 6.00 × (nc - 1)
	20 × 5 2LR version	2	$15.9 + 0.0228 \times (Abs. stroke + (nc - 1) \times A) + 6.0 \times (nc - 1)$	6.14 + 6.00 × (nc - 1)
SR-S		4 / 6 / 8 / 10	17.5 + 0.8* (n _{SA} -4) + 0.0228 × (Abs. stroke + (nc - 1) × A) + 6.0 × (nc - 1)	$6.42 + 0.07* (n_{SA} - 4) + 6.00 \times (nc - 1)$
110		0	8.2 + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.00 + 3.00 × (nc - 1)
	20 × 10	2	8.9 + 0.0144 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.07 + 3.00 × (nc - 1)
		4 / 6 / 8 / 10	9.7 + 0.4* (n $_{SA}$ -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.21 + 0.035* (n _{SA} -4) + 3.00 × (nc - 1)
		0	8.2 + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.00 + 3.00 × (nc - 1)
	20 × 20	2	$8.9 + 0.0144 \times (Abs. stroke + (nc - 1) \times A) + 3.0 \times (nc - 1)$	3.07 + 3.00 × (nc - 1)
		4 / 6 / 8 / 10	9.7 + 0.4* (n _{SA} -4) + 0.0114 × (Abs. stroke + (nc - 1) × A) + 3.0 × (nc - 1)	3.21 + 0.035* (n _{SA} -4) + 3.00 × (nc - 1)

Linear Unit	Ball screw	Number of SA	* Mass moment of inertia	* * * No load torque
	[d × l]	n _{SA}	[10 ⁵ kg m ²]	[Nm]
		0	5.6 + 0.0127 × (Abs. stroke + (nc - 1) × A) + 0.19 × (nc - 1)	0.23 + 0.23 × (nc - 1)
	20 × 5	2	$6.2 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.19 \times (nc - 1)$	0.26 + 0.23 × (nc - 1)
		4 / 6 / 8 / 10	7.0 + 0.4* (n _{SA} -4) + 0.0127 × (Abs. stroke + (nc - 1) × A) + 0.19 × (nc - 1)	$0.31 + 0.015^* (n_{SA} - 4) + .23 \times (nc - 1)$
	00 F	0	$9.5 + 0.0254 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.468 + 0.46 × (nc - 1)
	20 × 5 2LR version	2	$10.7 + 0.0254 \times (Abs. stroke + (nc - 1) \times A) + 0.38 \times (nc - 1)$	0.51 + 0.46 × (nc - 1)
SR-S		4 / 6 / 8 / 10	12.3 + 0.8* (n _{SA} -4) + 0.0254 × (Abs. stroke + (nc - 1) × A) + 0.38 × (nc - 1)	$0.62 + 0.03^{*} (n_{SA} - 4) + 0.46 \times (nc - 1)$
110		0	$6.2 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.25 + 0.25 × (nc - 1)
	20 × 10	2	$6.8 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)$	0.30 + 0.25 × (nc - 1)
		4 / 6 / 8 / 10	7.6 + 0.4* (n $_{SA}$ -4) + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 0.76 \times (nc - 1)	$0.41 + 0.025^* (n_{SA} - 4) + 0.25 \times (nc - 1)$
		0	$8.5 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 3.04 \times (nc - 1)$	0.30 + 0.30 × (nc - 1)
	20 × 20	2	$9.1 + 0.0127 \times (Abs. stroke + (nc - 1) \times A) + 3.04 \times (nc - 1)$	0.41 + 0.30 × (nc - 1)
		4 / 6 / 8 / 10	10.1 + 0.5* (n _{SA} -4) + 0.0127 × (Abs. stroke + (nc - 1) × A) + 3.04 × (nc - 1)	$0.62 + 0.055^* (n_{SA} - 4) + 0.30 \times (nc - 1)$

i

clamps.

* Absolute stroke [mm] A - Distance between carriages [mm]. More info on following pages.

nc - Number of carriages

** The stated values are for strokes (and for distances between the carriages A) up to 500mm

Unsupported profile length Lp [mm]

No Load Torque value increases with stroke (and with A) elongation.



In order to improve the products in this catalog the specifications are subject to change without notice.

Deflection of the linear unit

Mass calculation doesn't include mass of motor, reduction gear, switches and

Unsupported profile length Lp [mm]

Linear Unit doesn't include any safety Absolute stroke = Effective stroke + 2 x Safety stroke.



L_{SA} Additional length [mm]

Defining of the linear unit length

L = Effective stroke + 2 × Safety stroke + Lv + 2 × LSA + A × (nc - 1) + 15 mm

Ltotal = L + 90 mm, Lv = 330 mm





Mounting the drive

- by the MOTOR SIDE DRIVE MSD (Page 112)
- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.



Maximum travel speed as a function of the profile length (Vmax - L curves)

CHARACTERISTICS

The BR-E series Linear Unit is a powerful and cost-effective Linear Unit with toothed belt drive and a Zero-backlash Ball rail guide system for easy and accurate linear movements.

It can easily be combined to multi-axis systems.

Excellent price-/performance ratio and quick delivery time are ensured.

An extruded aluminum Profile from 6063 AL with on it mounted Zero-backlash Ball rail guide system, allows high load capacities and optimal cycles for the movement of larger masses at high speed.

The linear unit BR-E uses a pre-tensioned steel reinforced AT polyurethane timing toothed belt. In conjunction with a Zero-backlash drive pulley high moments with alternating loads with good positioning accuracy, low wear and low noise can be realized.

The aluminum Profile includes T-slots for fixing the Linear Unit and for attaching sensors and switches .

Different carriage lengths of the Linear Unit allow the possibility to attach additional accessories on the side.

Lubrication holes on the carriage allow easy re-lubrication of the Ball rail guide .

For the linear unit BR-E various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.



i The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0.35 mm/m; Max. torsion = 0.35 mm/m; Angular torsion = 0.2 mm/40 mm; Parallelism = 0.2 mm

STRUCTURAL DESIGN



- 1 Drive block with pulley
- 2 AT polyurethane toothed belt with steel tension cords
- 3 Carriage
- 4 Linear Ball Guideway
- 5 Belt Tensioning system
- 6 Lubrication port
- 7 Aluminium profile-Hard anodized
- 8 End block

HOW TO ORDER

BR	0040	E -	6000 -	L	20	X - 00
Series Prefix: BR Size: 0040: 40 Type: E						
Absolute stroke [mm]: (Absolute stroke = Effective stroke + 2 x Safety stro	oke)					
Carriage Version: S: Short L: Long						
Type of Drive Pulley: 00: Pulley with through hole 01: Pulley with journal 02: Pulley with journal on both sides 03: Without drive unit 10: Pulley with journal (without keyway) 20: Pulley with journal on both sides (without keyway)	vay)					
Drive Journal Position: L: Journal on left side R: Journal on right side X: Both sides or none						
Version:						

0S: Special version

01: Standard single carriage

02: Dual carriage

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i	Dynamic moment		Бо	Max.	permissi	ble loads	;	Moved mass	Max. Repeatat	bility	* Max. length	* Max. stroke	**Min. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm		Lmax [mm]	[mm]	[mm]
SR-S 40 S	132	9900	79	59	59	3270	5100	34	34	34	0.45	± 0.1		5000	5813	40
SR-S 40 L	200	19800	158	660	660	6540	10190	60	341	219	0.72	± 0.1		5960	5745	40
* For lengths	s / stroke ov	ver the stated value	in the ta	able abov	ve please	e contac	t us.	lincorun	it longth	for porti		ftho				
linear unit ne	eds to be i	used).	intiple ca	mages (quation	or defin	ing the	iniear un	lit length	ior parti	cular size of	i the	Оре	erating cor	ditions	
* For minim	um stroke	below the stated va	alue in th	e table a	bove ple	ease con	tact us.						Оре	erating tem	ıp. 0	°C ~ +60°C
									Z				Dut	y cycle		100%
i Reco	mmend	ed values of lo	bads						1				For o	perating te	mperature	e out of the
All th capa theo facto appli	ne data c cities sta retical w or. The sa ication a	of dynamic mo ated in the upp ithout conside afety factor de nd its requeste	oments per tab pring a pends ed safe	and lo le are ny safe on the ety.	oad et		¥_	Mx, M	Fpz, C	Mz, M	DZ OC		prese	ented range	e, piease c	ontact us.
We r	ecomme	end a minimur	n safe	y facto	n											
Mod	ulus of e	asticity									1					
E = 7	0000 N /	′ mm²				G	00			My, Mp	y Fpy, o	с				

General technical data for double carriage

Linear Unit	Carriage	Dynamic	*	* Dynamic moment			* Max. permissible loads					
	version	C [N]				For	ces	Moments				
			Mx [Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]		
00.0.40	S2	19800	158	9.9 × A	9.9 × A	6540	10190	68	5.1 × A	3.3 × A		
SR-S 40	L2	39600	317	19.8 × A	19.8 × A	13080	20380	120	10.2 × A	6.5 × A		

* A - Distance between carriages [mm]. More on page 4.030.0

Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Drive and belt data

i

Linear Unit	**Max. travel speed [m / s]	Max. drive torque [Nm]	* No load torque [Nm]	Puley drive ratio [mm / rev]	Pulley diameter [mm]	Belt type	Belt width [mm]	Max. force transmited by belt [N]	Specific spring constant Cspec [N]	** Max. acceleration [m/s ²]
SR-S 40 S	2	7.5	$1.0 \times nc$	100	F7 01	ATE	10	262	225000	70
SR-S 40 L	3	7.5	1.1 × nc	180	57.31	AI5	12	202	235000	70

* The stated values are for strokes (and for distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation. nc - Number of carriages

**For travel speed and acceleration over the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear Unit	Mass of linear unit	Mass moment of inertia	Planar m ine	oment of rtia
	[kg]	[10 ⁻⁵ kg m²]	ly [cm ⁴]	lz [cm ⁴]
BR-E 40 S	$3.1 + 0.003 \times (Abs. stroke + (nc - 1) \times A) + 0.45 \times (nc - 1)$	70.1 + 0.007 × (Abs. stroke + (nc - 1) × A) + 36.9 × (nc - 1)	0.52	0.21
BR-E 40 L	3.55 + 0.003 × (Abs. stroke + (nc - 1) × A) + 0.72 × (nc - 1)	92.3 + 0.007 × (Abs. stroke + (nc - 1) × A) + 59.1 × (nc - 1)	9.55	9.21

* Absolute stroke [mm]

A - Distance between carriages [mm]. More info on following pages.

nc - Number of carriages

1 Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit



BR-E 40





TYPE 0



TYPE 1 L and 1 R





Ø62 H7

1.5 mm Deep

[0]

3 P9/h9

Ø10 h7

TYPE 2

450

38.325

In order to improve the products in this catalog the specifications are subject to change without notice.



CHARACTERISTICS

The BR-Z series contains Z-axis Linear Units with toothed belt drive, integrated Ball rail system and compact dimensions. This Linear Units provide high performance features such as, high speed, good accuracy and repeatability by vertical applications.

They can easily be combined to multi-axis systems.

Excellent price-/performance ratio and quick delivery time are ensured.

The compact, precision-extruded aluminum Profile from 6063 AL with integrated Zero-backlash Ball rail guide system, allows high load capacities and optimal cycles for the movement of larger masses at high speed.

In the linear units BR-Z is used a pre-tensioned steel reinforced AT polyurethane timing toothed belt. In conjunction with a Zero-backlash drive pulley high moments with alternating loads with good positioning accuracy, low wear and low noise can be realized.

The in the Profile slot driving Polyurethane timing belt protects all the parts in the Profile from dust and other contaminations.

The aluminum Profile includes T-slots for attaching sensors and switches. Also, a Reed switch can be used here.

The drive block provides the possibility to attach a Motor or Gearbox housing and additional accessories on it.

Central lubrication port on the drive block allows easy re-lubrication of the Ball rail guide.

For the linear units BR-Z various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.



i The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0.35 mm/m; Max. torsion = 0.35 mm/m; Angular torsion = 0.2 mm/40 mm; Parallelism = 0.2 mm

STRUCTURAL DESIGN



- 1 Tension End with integrated belt tensioning system
 2 AT polyurethane toothed belt with steel tension cords
 3 Aluminium profile-Hard anodized

- 4 Linear Ball Guideway
- 5 Drive block with pulley, Motor flange; with built in Magnets
- 6 Central lubrication port; both sides
- 7 Tension End with integrated belt tensioning system
- 8 Clamping and braking element for linear guideway

HOW TO ORDER

Series Prefix:		BR 011	0 Z - 3000	- 20	1 - 1	0
Absolute stroke [mm]:	Series Prefix: BR Size: 0040: 40 0065: 65 0080: 80 0110: 110 Series Suffix: Z					
Type of Drive Pulley:	Absolute stroke [mm]: (Absolute stroke = Effective stroke + 2 x	Safety stroke)				
Number of Drive Blocks:	Type of Drive Pulley:) ithout keyway) on 00				
Clamping Element:	Number of Drive Blocks: The stated number specifies the numbe	er of drive blocks o	n one Linear Unit			
	Clamping Element: 0: Without 1: With (available only for BR0110Z)					

S: Special version

1: Standard single carriage

2: Dual carriage

General technical data

Linear Unit	Drive block length	i Dynamic load capacity	i Dyr	iamic mo	ment	Mass of drive block	Maximum Repeatability	² Max. length	2 Max. length	² Ma Stro	x. ke	¹ Min. Stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	[kg]	[mm]	³ (Version 1) Lmax [mm]	³ (Version 2) Lmax [mm	³ (Ver. 1) [mm]	³ (Ver. 2) [mm]	[mm]
BR-Z 40	120	4610	28	120	120	0.95	±0.08	1000	3000	792	2792	25
¹ For mini	mum stroke be	low the stated valu	e in the ta	ble above	e please co	ntact us.						
² For leng Values fo particula	ths / stroke ove or max. stroke a r size of the lin	r the stated value i are not valid for mu ear unit needs to b	n the table Iltiple driv e used).	e above pl e blocks (ease conta equation o	ct us. f defining the linear	r unit length for	Lind Ur	ear hit For Fpy	Max. permiss ces Fpz Mpx	ble load Momen	s ts Mpz
³ Moun	ting versior	ıs						BR-2	[N] Z 40 2320	1510 14	40	[Nm] 62
Versio	n 1: Mountin	a by the drive bl	ock. prof	ile trave	ls							
F====			· · · / · ·						Ope	rating conditi	ons	
		0 •							Ope	rating temp.	0°C	~ +60°C
		•							Duty	cycle		100%
Versio	n 2: Mountin	a by the profile.	drive blo	cks trav	el				For op preser	erating temp nted range, pl	erature c ease con	ut of the tact us.
Multiple	e drive blocks, v	A Constraints of the second se	endently o	f each oth	ner, can be	applied.		لار	Fpz, C Mx, Mpx	Mz, Mpz		
i R	ecommend	ed values of lc	ads)
All the table a depend minimu	data of dyn re theoretic Is on the ap um safety fa	amic moment al without con oplication and actor (fs =5.0)	s and lo sidering its requ	ad cap g any sa ested s	acities s afety fac afety. W	tated in the up tor. The safety e recommend	per factor a			My, Mpy	Fp	y, C
Moduli	us of elastic	ity: E = 70000	N / mm	1				0	-			
Drive a	ind belt d	ata										

Linear Unit	* Max. travel speed	Max. drive torque	Max. drive No load torque of drive block		Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant C _{spec}	* Max. acceleration	
	[m / s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]	
BR-Z 40	5	3.6	0,2	99	31.51	AT3	20	230	225000	70	

 \ast For travel speed and acceleration over the stated value in the table above please contact us.

Mass and planar moment of inertia

Linear Unit	* Mass of linear unit	Planar n inc	noment of ertia
	[kg]	ly [cm ⁴]	lz [cm ⁴]
BR-Z 40	$1.7 + 0,0023 \times (Abs. stroke + (nb - 1) \times A) + 0.95 \times (nb - 1)$	9.8	11.6
*Absolute stroke [mm]			

A - Distance between two drive blocks [mm] nb - Number of drive blocks

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Mass moment of inertia

Linear Unit	* Mass moment of inertia (Version 1) [10 ⁻⁴ kg m ²]	Mass moment of inertia of drive block (Version 2) [10 ⁻⁴ kg m ²]
BR-Z 40	2.1 + 0.0058 × (Abs. stroke + (nb - 1) × A) + 0.22 × (nb - 1)	2.6
* Absolute stroke [mm		

A - Distance between two drive blocks [mm]

nb - Number of drive blocks

Deflection of the linear unit



BR-Z 40







All dimensions in mm; Drawings scales are not equal.

TYPE 0





TYPE 1









All dimensions in mm; Drawings scales are not equal.

Defining of the linear unit length

L = Effective stroke + $2 \times \text{Safety stroke} + 208 \text{ mm}$

Ltotal = L + 24 mm





General technical data

Linear Unit	Drive block length	i Dynamic load capacity	i Dyr	iamic moi	ment	Mass of drive block	Maximum Repeatability	² Max. length	² Max. length	2 M Str	ax. oke	¹ Min. Stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	[kg]	[mm]	³ (Version 1) Lmax [mm]	³ (Version 2) Lmax [mm]	³ (Ver. 1) [mm]	³ (Ver. 2) [mm]	[mm]
BR-Z 65	200	19800	158	1025	1025	3.2	±0.08	1200	6000	880	5680	40
1												

¹ For minimum stroke below the stated value in the table above please contact us.

² For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple drive blocks (equation of defining the linear unit length for particular size of the linear unit needs to be used).

³ Mounting versions

Version 1: Mounting by the drive block, profile travels



Version 2: Mounting by the profile, drive blocks travel



Multiple drive blocks, which travel independently of each other, can be applied.

i Recommended values of loads

All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)

Modulus of elasticity: $E = 70000 \text{ N} / \text{mm}^2$

	Linear	Max. permissible loads							
	Unit	For	ces	Moments					
		Fpy Fpz [N] [N]		Mpx [Nm]	Mpy [Nm]	Mpz [Nm]			
j	BR-Z 65	6540	5870	60	305	340			

Operating conditions	
Operating temp.	$0^{\circ}C \sim +60^{\circ}C$
Duty cycle	100%

For operating temperature out of the presented range, please contact us.



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant Cspec	* Max. acceleration
	[m / s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BR-Z 65	5	13.1	0.9	165	52.52	AT5	32	500	600000	70

* For travel speed and acceleration over the stated value in the table above please contact us.

Mass and planar moment of inertia

Linear Unit	* Mass of linear unit	Planar n ine	homent of ertia
	[kg]	ly [cm ⁴]	lz [cm ⁴]
BR-Z 65	5.7 + 0.0054 × (Abs. stroke + (nb - 1) × A) + 3.2 × (nb - 1)	59.7	74.4
* Alegelute studie frame			

i

* Absolute stroke [mm] A - Distance between two drive blocks [mm]

nb - Number of drive blocks

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Mass moment of inertia

Linear Unit	* Mass moment of inertia (Version 1) [10 ⁻⁴ kg m ²]	Mass moment of inertia of drive block (Version 2) [10 ⁻⁴ kg m ²]
BR-Z 65	$18.9 + 0.0374 \times (Abs. stroke + (nb - 1) \times A) + 1.7 \times (nb - 1)$	23.8
*Absolute stroke [mm]		

A - Distance between two drive blocks [mm]

nb - Number of drive blocks

Deflection of the linear unit



BR-Z 65







i All dimensions in mm; Drawings scales are not equal.

TYPE 0 TYPE 1 TYPE 2 i Journal with or without Keyway. i Journal with or without Keyway. 5 P9 6 æ Ć ¢ Ø42 H7 2.25 mm Deep Ø16 h7 5 P9/h9 DIN 6885 A Ø42 H7 Ø42 H7 2.25 mm Deep 2.25 mm Deep 32 -0 φ ф -\$ ø 0 -0 ¢ **•**-¢ Ø42 H7 32 32 2 2.25 mm Deep 5.5 5 P9/h9 5 P9/h9 DIN 6885 A Ø42 H7 DIN 6885 A

In order to improve the products in this catalog the specifications are subject to change without notice.

Ø42 H7 2.25 mm Deep

Ø16 h7

Ø16 h7

2.25 mm Deep



All dimensions in mm; Drawings scales are not equal.

Defining of the linear unit length

L = Effective stroke + $2 \times$ Safety stroke + 320 mm

Ltotal = L + 40 mm



General technical data

Linear Unit	Drive block length	i Dynamic Ioad capacity	i Dyn	amic moi	ment	Mass of drive block	Maximum Repeatability	² Max. length	² Max. length	² Ma Stro	x. ke	¹ Min. Stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	[kg]	[mm]	³ (Version 1) Lmax [mm]	³ (Version 2) Lmax [mm]	³ (Ver. 1) [mm]	³ (Ver. 2) [mm]	[mm]
BR-Z 80	250	34200	370	2565	2565	4.9	±0.08	1500	6000	1118	5618	55
¹ For mini	mum stroke be	low the stated valu	e in the ta	ble above	please co	ntact us.						
² For leng Values f particula	ths / stroke ove or max. stroke a ar size of the lin	er the stated value i are not valid for mu ear unit needs to b	n the table ultiple driv e used).	above pl e blocks (ease conta equation o	ct us. f defining the linear	r unit length for	Line Ur	ear M ^{hit} Force Fpy	lax. permissi es Fpz Mpx	ble load Momen Mpy	s ts Mpz
³ Moun	ting versior	าร						BR-	Z 80 8930	7130 150	535	670
Versio	n 1: Mountin	a by the drive bl	ock. prof	ile trave	ls							
le===		5 · · / · · · · · · · · · · · ·			-				Opera	ating condition	ons	
		0							Opera	iting temp.	0°C	~ +60°C
		• •							Duty	cycle		100%
Versio	Version 2: Mounting by the profile drive blocks travel									rating temp ed range, pl	erature c ease con	ut of the tact us.
Volutio		g by the promo,			01							
0			••••	0					Fpz, C			
Multipl	e drive blocks,	which travel indepe	endently o	feach oth	er, can be	applied.				Mz, Mpz		
i R	ecommend	ed values of lo	ads					**	Mx, Mpx) '
All the table a depend minim	data of dyn re theoretic ds on the ap um safety fa	amic moment al without con oplication and actor (fs =5.0)	s and lo sidering its requ	ad cap any sa ested s	acities stafety fac afety. W	tated in the up tor. The safety e recommend	per factor a			My, Mpy	Fp	y, C
Moduli	us of elastic	ity: E = 70000	N / mm	2				0	~			
Drive a	and belt d	lata										

Linear Uni	Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant C _{spec}	* Max. acceleratio
	[m / s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BR-7 80	5	29.4	1.4	210	66 84	AT5	50	880	960000	70

* For travel speed and acceleration over the stated value in the table above please contact us.

Mass and planar moment of inertia

Linear Unit	* Mass of linear unit	Planar n ine	noment of ertia
	[kg]	ly [cm ⁴]	lz [cm ⁴]
BR-Z 80	$9.7 + 0.0083 \times (Abs. stroke + (nb - 1) \times A) + 4.9 \times (nb - 1)$	129.1	173.4
* Absoluto stroko [mm	1		

* Absolute stroke [mm] A - Distance between two drive blocks [mm] nb - Number of drive blocks

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Mass moment of inertia

Linear Unit	* Mass moment of inertia (Version 1) [10-4 kg m ²]	Mass moment of inertia of drive block (<i>Version 2</i>) [10⁻⁴ kg m ²]
BR-Z 80	60.0 + 0.0922 × (Abs. stroke + (nb - 1) × A) + 6.4 × (nb - 1)	61.1
* Absolute stroke [mm]		

A - Distance between two drive blocks [mm] nb - Number of drive blocks

Deflection of the linear unit



BR-Z 80







All dimensions in mm; Drawings scales are not equal.

TYPE 0





TYPE 1



Journal with or without Keyway.
Ø50 H7
 30 2 mm Deep







All dimensions in mm; Drawings scales are not equal.

Defining of the linear unit length

L = Effective stroke + $2 \times$ Safety stroke + 382 mm

Ltotal = L + 44 mm



L = Effective stroke + 2 × Safety stroke + A × (nb - 1) + 382 mm

Ltotal = L + 44 mm

A ≥ 250 mm 📕

General technical data

Linear Unit	Drive block length	i Dynamic load capacity	i Dyr	i Dynamic moment		Mass of drive block	Maximum Repeatability	² Max. length	² Max. length	2 M Str	ax. oke	¹ Min. Stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	[kg]	[mm]	³ (Version 1) Lmax [mm]	³ (Version 2) Lmax [mm]	³ (Ver. 1) [mm]	³ (Ver. 2) [mm]	[mm]
BR-Z 110	300	49600	630	3470	3470	11.3	±0.08	1800	6000	1304	5504	65

¹ For minimum stroke below the stated value in the table above please contact us.

 $^{2}\,$ For lengths / stroke over the stated value in the table above please contact us.

Values for max, stroke are not valid for multiple drive blocks (equation of defining the linear unit length for particular size of the linear unit needs to be used).

³ Mounting versions

Version 1: Mounting by the drive block, profile travels



Version 2: Mounting by the profile, drive blocks travel



Multiple drive blocks, which travel independently of each other, can be applied.



Recommended values of loads

All the data of dynamic moments and load capacities stated in the upper table are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0)

Modulus of elasticity: $E = 70000 \text{ N} / \text{mm}^2$



Operating conditions						
Operating temp.	$0^{\circ}C \sim +60^{\circ}C$					
Duty cycle	100%					

For operating temperature out of the presented range, please contact us.



Drive and belt data

Linear Unit	* Max. travel speed	Max. drive torque	No load torque of drive block	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant Cspec	* Max. acceleration
	[m / s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BR-Z 110	5	110.0	2.6	300	95.49	AT10	70	2300	2450000	70

* For travel speed and acceleration over the stated value in the table above please contact us.

Mass and planar moment of inertia

Linear Unit	* Mass of linear unit	Planar moment of inertia		
	[kg]	ly [cm ⁴]	lz [cm ⁴]	
BR-Z 110	21.7 + 0.0147 × (Abs. stroke + (nb - 1) × A) + 11.3 × (nb - 1)	513.0	620.0	
* Abashuta studio [man]				

i

Absolute stroke [mm]

A - Distance between two drive blocks [mm] nb - Number of drive blocks

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Mass moment of inertia

Linear Unit	* Mass moment of inertia (Version 1) [10 ⁻⁴ kg m ²]	Mass moment of inertia of drive block (Version 2) [10 ^{.4} kg m ²]
BR-Z 110	282.4 + 0.3358 × (Abs. stroke + (nb - 1) × A) + 45,3 × (nb - 1)	302.9
* Absolute stroke [mm]		

A - Distance between two drive blocks [mm]

nb - Number of drive blocks

Deflection of the linear unit



BR-Z 110 -






All dimensions in mm; Drawings scales are not equal.

TYPE 0





Drive block with clamping element

Clamping by spring-loaded energy



Air pressure = 0 bar

Holding force = 1400 N

Holding force is tested on clamping element using a slightly lubricated rail (ISO VG 68).

Opened by air pressure



Opening air pressure = 5.5 - 8 bar

The air pressure opens clamping pistons. Free movement is allowed.

Purified and oiled air shall be used (according to ISO 8573-1 Class 4). Recommended filter size is 25 $\mu m.$

Linear Unit	Mass of drive block [kg]	* Mass of linear unit [kg]
BR-Z 110	12.9	23.3 + 0.0147 × (Abs. stroke + (nb - 1) × A) + 12.9 × (nb - 1)

* Absolute stroke [mm] A - Distance between two drive blocks [mm] nb - Number of drive blocks



```
All dimensions in mm; Drawings scales are not equal.
```

Defining of the linear unit length

L = Effective stroke + $2 \times Safety stroke + 496 mm$

Ltotal = L + 46 mm



L = Effective stroke + 2 × Safety stroke + A × (nb - 1) + 496 mm

Ltotal = L + 46 mm

[^]A ≥ 300 mm

A ≥ 410 mm

۱

In case of using the drive blocks with clamping element

CHARACTERISTICS

The BR-D series includes Linear Units with a toothed belt drive and two parallel, integrated, Zero-backlash rail guides. Compact dimensions allow high performance features such as, high speed and repeatability.

They can easily be combined to multi-axis systems.

Excellent price-/performance ratio and quick delivery time are ensured.

A compact , precision-extruded aluminum Profile from AL 6063, with two parallel, integrated Zero-backlash rail guide systems, allows high load capacities and an optimal sequence for the movement of larger masses at high speed.

In the linear units BR-D is used a pre-tensioned steel reinforced AT polyurethane timing toothed belt. In conjunction with a Zero-backlash drive pulley high moments with alternating loads with good positioning accuracy, low wear and low noise can be realized.

The in the Profile slot driving Polyurethane timing belt, protects all the parts in the Profile from dust and other contaminations.

Different carriage lengths with lubrication port allows for easy re-lubrication of the Ball rail guide system and allows the possibility to attach additional accessories. The re-lubrication can also be done through maintenance holes on the side of the Profile.

The aluminum profile includes T-slots for fixing the Linear Unit and for attaching sensors and switches. Also, a Reed switch can be used here.

For the linear units BR-D various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.



The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0.35 mm/m; Max. torsion = 0.35 mm/m; Angular torsion = 0.2 mm/40 mm; Parallelism = 0.2 mm

STRUCTURAL DESIGN



- 1 Drive block with floating bearing
- 2 Gap-type seal of antistatic PU strip (recirculating)
- 3 Ball screw tolerance ISO7 (ISO5 available on request)
- 4 Carriage; with built in Magnets
- 5 Aluminum cover
- 6 Aluminium profile-Hard anodized
- 7 Two integrated Linear Ball Guideways
- 8 Central lubrication port; both sides
- 9 End block with fixed bearing

HOW TO ORDER

BR 0200 D - 6000 - L 20 R - 1	0
Series Prefix:BR	
Size:	
Series Suffix:	
Absolute stroke [mm]:	
Carriage Version: —	
Type of Drive Pulley:	
Drive Journal Position:	
R: Journal on right side X: Both sides or none	
Connection Plate:	
0: Without 1: With	
Version:	
S: Special version	

1: Standard single carriage

2: Dual carriage

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i	Dynamic moment		For	Max. ces	permiss I	ible loac Moments	ls s	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	^{XX} Min. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-D 90 S	102	4620	125	17	34	2000	4000	110	17	34	0.20	+ 0.08	0000	5873	25
BR-D 90 L	156	9240	250	290	290	3990	8270	200	290	125	0.35	+ 0.08	6000	5819	25
* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).															
** For min	nimum strok	e below the stated	value in th	ne table al	bove plea	ise cont	tact us.						Operating ten	p. 0°	C ~ +60°C
										Z			Duty cycle		100%
Image: Duty cycle Duty cycle 100% For operating temperature out of the presented range. please contact us.															
All the c stated in conside depends We reco	lata of dy n the upp ring any s s on the a mmend a	namic momer er table are the safety factor. T application and a minimum sa	nts and eoretica The safe I its req fety fact	load ca Il witho ty facto uested tor (fs =	pacitie ut or safety. 5.0)	S	بط	Mx	. Mpx	000	~	>			
Modulu	s of elast	icity							>/		R				
E = 7000	00 N / mm	12					R			My.	. Мру	Fpy. C			

General technical data for double carriage

Carriage	Dynamic	*	Dynamic moment		* Max. permissible loads						
version	load capacity				Forces			Moments	Moments		
	C[N]	Mx[Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	M _{PY} [Nm]	Mpz [Nm]		
S2	9230	250	$4.6 \times A$	4.6 × A	4000	8000	220	4.0 × A	2.0 × A		
L2	18400	500	9.2 × A	9.2 × A	8000	16500	400	8.3 × A	4.0 imes A		
	Carriage version S2 L2	Carriage Dynamic load capacity C [N] S2 9230 L2 18400	Carriage version Dynamic load capacity * C[N] Mx[Nm] S2 9230 L2 18400	Carriage version Dynamic load capacity * Dynamic moment C[N] Mx [Nm] My [Nm] S2 9230 250 4.6 × A L2 18400 500 9.2 × A	Carriage version Dynamic load capacity Dynamic moment C[N] Mx[Nm] My[Nm] Mz[Nm] S2 9230 250 4.6 × A 4.6 × A L2 18400 500 9.2 × A 9.2 × A	Carriage version Dynamic load capacity * Dynamic moment * For C[N] Mx [Nm] My [Nm] Mz [Nm] Fpy [N] S2 9230 250 4.6 × A 4.6 × A 4000 L2 18400 500 9.2 × A 9.2 × A 8000	Carriage version Dynamic load capacity * Dynamic moment * Forces C[N] Mx [Nm] My [Nm] Mz [Nm] Fpy [N] Fpz [N] S2 9230 250 4.6 × A 4.6 × A 4000 8000 L2 18400 500 9.2 × A 9.2 × A 8000 16500	Carriage version Dynamic load capacity * Dynamic moment * Max. performance C[N] Mx [Nm] My [Nm] Mz [Nm] Fpr [N] Fpr [N] Mpx [Nm] S2 9230 250 4.6 × A 4.6 × A 4000 8000 220 L2 18400 500 9.2 × A 9.2 × A 8000 16500 400	Carriage version Dynamic load capacity * Dynamic moment * Max. permissible loads Moments C[N] Mx[Nm] My[Nm] Mz[Nm] Fpy[N] Fpz[N] Mpx[Nm] Mpv[Nm] S2 9230 250 4.6 × A 4.6 × A 4000 8000 220 4.0 × A L2 18400 500 9.2 × A 9.2 × A 8000 16500 400 8.3 × A		

* A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Drive and belt data

i

Linear Unit	** Max. travel speed	Max. drive torque [Nm]	* No load torque [Nm]	Puley drive ratio	Pulley diameter [mm]	Belt type	Belt width	Max. force transmited by belt [N]	Specific spring constant C _{spec}	** Max. acceleration [m/s²]	
	1			[1.11/01	
BR-D 90 S	5	7.5	$0.40 \times nc$	00	29.65	AT 2	25	520	402500	70	
BR-D 90 L	5	7.5	0.42 × nc	90	20.05	AIS	35	520	402500	70	

* The stated values are for strokes (and distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages ** For travel speed and acceleration over the stated value in the table above please contact us.



Defining of the linear unit length





BR-D 90 L





Lubrication nipple DIN 3405D (both sides)

BR-D 90 S

CONNECTION PLATE







Lubrication nipple DIN 3405D (both sides)

Slot nut More info at page 117

L

5

7.6

F





Linear Unit	Plate length [mm]	Weight [kg]	Code
BR-D 90 S	60	0.2	103661
BR-D 90 L	125	0.4	103660

Mounting elements for mounting the connection plate on the Linear unit are inlcuded.

Mounting the drive

- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i	Dynamic moment		For	Max. ces	permiss	ible loac Moments	ls s	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	^{XX} Min. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-D 110 S	170	19800	610	118	235	6470	8390	260	90	90	0.64	+ 0.08	6000	5805	40
BR-D 110 L	215	39600	1225	1680	1680	13080	18820	525	880	550	0.98	+ 0.08	0000	5760	40
* For lengths / stroke over the stated value in the table above please contact us. Values for max, stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used). ** For minimum stroke below the stated value in the table above please contact us. Operating conditions															
** For mir	nimum strok	e below the stated	value in th	ie table a	bove plea	ase cont	act us.						Operating ten	np. 0°	C ~ +60°C
										Z			Duty cycle		100%
All the c stated in conside depends We reco Modulu E = 7000	comment lata of dy n the upp ring any s s on the a ommend a s of elast 00 N / mm	led values of lo namic momer er table are the safety factor. T application and a minimum sa icity n ²	bads hts and eoretica 'he safe I its req fety fact	oad ca l witho ty facto uested cor (fs =	pacitie ut safety. 5.0)	s	J.	Mx	Fpz. C	Mz.	Mpz Mpy	Fpy. C	or operating t resented rang	emperature e. please co	out of the ntact us.

General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic moment		* Max. permissible loads					
Unit	version	load capacity				Forces			Moments		
			Mx[Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	
PP D 110	S2	39600	1220	19.8 × A	19.8 × A	12940	16770	520	8.4 × A	6.5 × A	
DR-D I IU	L2	79200	2450	39.6 × A	39.6 × A	26150	37600	1050	18.8 × A	13.1 × A	

*A - Distance between carriages [mm]. More info on following pages.

i Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Drive and belt data

Linear Unit	* * Max. travel speed	Max. drive torque	* No load torque	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant C _{spec}	** Max. acceleration	
	[111/5]			[IIIII / IEV]	[!!!!!]		[[11/5]	
BR-D 110 S	6	15 7	0.98 × nc	120	38.20	ΔT 5	50	820	960000	70	
BR-D 110 L	5		1.00 × nc	.20	00.20	/0	50	020	00000	70	

* The stated values are for strokes (and distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages ** For travel speed and acceleration over the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear Unit	Mass of linear unit	Mass moment of inertia	Planar moment of inertia		
	[kg]	[10 ⁻⁵ kg m²]	ly [cm ⁴]	lz [cm ⁴]	
BR-D 110 S	3.6 + 0.0072 × (Abs. stroke + (nc - 1) × A) + 0.64 × (nc - 1)	36 + 0.0125 × (Abs. stroke + (nc - 1) × A) + 23.3 × (nc - 1)	21.1	217.2	
BR-D 110 L	4.2 + 0.0072 × (Abs. stroke + (nc - 1) × A) + 0.98 × (nc - 1)	49 + 0.0125 × (Abs. stroke + (nc - 1) × A) + 35.8 × (nc - 1)	31.1	217.2	
A* Absolute st	roke [mm]				

A - Distance between carriages [mm]. More info on following pages.

nc - Number of carriages

1 Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit



BR-D 110 2.5 0.6 0.5 2.0 Deflection d [mm] Deflection d [mm] = 0 N = 10 N = 25 N = 50 N = 100 N = 200 N = 500 N = 0 N = 50 N = 125 N = 250 N = 500 N = 750 N 0.4 91 1.5 0.3 1.0 1200 0.2 0.5 0.1 0.0 ^上 0 0.0 1000 2000 3000 4000 0 200 400 600 800 1000 Unsupported profile length Lp [mm] Unsupported profile length Lp [mm]



Defining of the linear unit length



Ε

8



CONNECTION PLATE

BR-D 110 S

BR-D 110 L



Slot nut More info at page 8.005.0



Linear Unit	Plate length [mm]	Weight [kg]	Code
BR-D 110 S	60	0.35	103663
BR-D 110 L	155	0.60	103662

Mounting elements for mounting the connection plate on the Linear unit are inlcuded.

Mounting the drive

- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i	Dynamic moment		For	Max. [.] ces	permiss	ible load Moment	ds s	Moved mass	Max. Repeatability	* Max. length	* Max. stroke	^{XX} Min. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-D 145 S	180	34200	1500	260	520	8930	15320	674	260	180	1.35	+ 0.08	6000	5795	55
BR-D 145 L	240	68400	3005	3420	3420	17870	30640	1200	1700	893	2.25	+ 0.08	0000	5735	55
* For lengtl Values for r the linear u	hs / stroke c max. stroke init needs to	over the stated value are not valid for me be used).	e in the ta ultiple car	ble above riages (ec	please c juation of	ontact u f definir	us. ng the li	near un	it length	for parti	icular size	of	Operating co	nditions	
** For min	imum strok	e below the stated	value in tł	ne table a	bove plea	ase cont	tact us.						Operating ter	np. 0	°C ~ +60°C
										Z			Duty cycle		100%
i Reco All the d stated in consider depends We reco Modulus E = 7000	ommend lata of dy i the upp ring any s on the a mmend s of elast 0 N / mn	ed values of lo mamic momer er table are the safety factor. T application anc a minimum sa icity 1 ²	bads hts and eoretica he safe I its req fety fac	load ca I witho ty facto uested tor (fs =	pacitie ut safety. ₅5.0)	s	L	M×	Fpz. C	Mz.	Mpz Mpy	Fpy. C	For operating t	emperature e. please co	out of the ntact us.

General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic moment		* Max. permissible loads						
Unit	version	load capacity C [N]				For	ces		Moments			
			Mx[Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]		
BB D 145	S2	68400	3000	34.2 × A	34.2 × A	17870	30640	1350	15.3 × A	8.9 × A		
DI1-D 145	L2	136800	6000	68.4 × A	68.4 × A	35700	61200	2400	30.6 × A	17.8 × A		

*A - Distance between carriages [mm]. More info on following pages.

i Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Drive and belt data

Linear Unit	* * Max. travel speed	Max. drive torque	Max. drive No load torque f		Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant C _{spec}	** Max. acceleration
	[m/s]	[NM]	[NM]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s ⁻]
BR-D 145 S	c	22.6	1.48 × nc	165	52 52	AT E	70	1290	1260000	70
BR-D 145 L	0	33.0	1.50 × nc	105	52.52	AT 5	70	1200	1300000	70

* The stated values are for strokes (and distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation. nc - Number of carriages

* For travel speed and acceleration over the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear Unit	Mass of linear unit	Mass moment of inertia	Planar moment of inertia		
	[kg]	[10 ⁻⁵ kg m²]	ly [cm ⁴]	lz [cm ⁴]	
BR-D 145 S	7.2 + 0.0127 × (Abs. stroke + (nc - 1) × A) + 1.35 × (nc - 1)	$145 + 0.0330 \times (Abs. stroke + (nc - 1) \times A) + 93.1 \times (nc - 1)$	79.0	707.6	
BR-D 145 L	8.8 + 0.0127 × (Abs. stroke + (nc - 1) × A) + 2.25 × (nc - 1)	208 + 0.0330 × (Abs. stroke + (nc - 1) × A) + 155.2 × (nc - 1)	70.9	/0/.0	

*Absolute stroke [mm] A - Distance between carriages [mm]. More info on following pages.

nc - Number of carriages

i Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit







Defining of the linear unit length



CONNECTION PLATE

BR-D 145 S



BR-D 145 L



Mounting elements for mounting the connection plate on the Linear unit are inlcuded

Mounting the drive

- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.

General technical data

Linear Unit	Carriage length	i Dynamic Ioad capacity	i	Dynamic moment	:	Max. permissible loads Moved Max. Forces Moments mass Repeatabil					Max. Repeatability	* Max. length	* Max. stroke	^{**} Min. stroke	
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	[mm]	Lmax [mm]	[mm]	[mm]
BR-D 200 S	265	49600	3235	450	900	10000	24520	1600	450	308	3.05	+ 0.08	6000	5710	65
BR-D 200 L	405	99200	6470	8680	8680	20000	50900	3250	4550	1750	5.70	+ 0.08	0000	5570	65
* For lengt Values for the linear u	hs / stroke c max. stroke init needs to	over the stated valu are not valid for m o be used).	e in the ta ultiple car	ble above riages (ec	please c juation o	ontact (f definir	us. ng the li	near un	it length	for part	icular size	of	Operating co	nditions	
* For mini	mum stroke	below the stated v	alue in the	e table ab	ove pleas	se conta	ict us.						Operating ter	np. C	°C ~ +60°C
										z			Duty cycle		100%
All the d stated in conside depends We reco Modulus E = 7000	ommend lata of dy n the upp ring any s on the a mmend s of elast 00 N / mn	ed values of lo mamic momer er table are thi safety factor. T application and a minimum sa icity n ²	bads eoretica The safe I its req fety fact	load ca I witho ty facto uested tor (fs =	pacitie ut safety. 5.0)	S	L	Mx	Fpz. C	Mz.	Mpz Mpy	Fpy. C	For operating t	emperaturd	e out of the ontact us.

General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic moment	:	* Max. permissible loads						
Unit	version						ces		Moments			
		C[N]	C[N] Mx[Nm] My[Nm] Mz		Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]		
BB D 200	S2	99200	6470	49.6 × A	49.6 × A	20000	49040	3200	24.5 × A	10.0 × A		
BN-D 200	L2	198400	12940	99.2 × A	99.2 × A	40000	101800	6500	50.9 × A	20.0 × A		

* A - Distance between carriages [mm]. More info on following pages.

i Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Drive and belt data

Linear Unit	* * Max. travel speed	Max. drive torque	* No load torque	Puley drive ratio	Pulley diameter	Belt type	Belt width	Max. force transmited by belt	Specific spring constant Cspec	** Max. acceleration
	[m/s]	[Nm]	[Nm]	[mm / rev]	[mm]		[mm]	[N]	[N]	[m/s²]
BR-D 200 S	6	102 with keyway	3.5 × nc	250	70 59	AT 10	100	2850	4250000	70
BR-D 200 L	0	113 without keyway	$4.5 \times nc$	250	/9.56	ALIO	100	2000	4350000	70

* The stated values are for strokes (and distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages ** For travel speed and acceleration over the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear Unit	Mass of linear unit	Mass moment of inertia	Planar m ine	oment of rtia
	[kg]	[10 ⁻⁵ kg m²]	ly [cm ⁴]	lz [cm ⁴]
BR-D 200 S	20.2 + 0.0245 × (Abs. stroke + (nc - 1) × A) + 3.1 × (nc - 1)	778 + 0.1868 × (Abs. stroke + (nc - 1) × A) + 482.9 × (nc - 1)	276 /	2744.6
BR-D 200 L	26.2 + 0.0245 \times (Abs. stroke + (nc - 1) \times A) + 5.7 \times (nc - 1)	1210 + 0.1868 × (Abs. stroke + (nc - 1) × A) + 902.4 × (nc - 1)	570.4	2744.0
* Absolute stro	ke [mm]			

A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages

i Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit







Ø16 H7

page <u>116</u>

¹40^{±0.01}

41±0.01

3.1 mm Deep (8x)

0

0

For centering ring CR 16 Accessories see on

DIMENSIONS



CONNECTION PLATE

BR-D 200 S







i All dimensions in mm; Drawings scales are not equal.

BR-D 200 L 305





Linear Unit	Plate length [mm]	Weight [kg]	Code
BR-D 200 S	190	2.3	395-103667
BR-D 200 L	305	3.7	395-103666

Mounting elements for mounting the connection plate on the Linear unit are inlcuded

Mounting the drive

- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.

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i

CHARACTERISTICS

The SR-D series describes Linear Units with a precision ball screw drive and two parallel, integrated, Zero-backlash rail guides. Compact dimensions allow high performance features such as, high speeds, good accuracy and repeatability.

They can easily be combined to multi-axis systems.

Excellent price-/performance ratio and quick delivery time are ensured.

The compact, precision-extruded aluminum Profile from AL 6063, with two parallel, integrated, Zero-backlash rail guide systems, allows high load capacities and optimal cycles for the movement of larger masses at high speed.

In the Linear Units SR-D a precision ball screw, with tolerance class ISO7 (ISO5 on request), with reduced backlash of the ball nut is used.

Two parallel circulating antistatic polyurethane sealing strips and an aluminum cover are ensuring to protect all the parts in the profile from dust and other contaminantions.

Different carriage lengths with lubrication port allows for easy re-lubrication of the ball screw and Ball rail guide system and allows the possibility to attach additional accessories. The re-lubrication can also be done through maintenance holes on the side of the Profile.

The aluminum profile includes T-slots for fixing the Linear Unit and for attaching sensors and switches. Also, a Reed switch can be used here.

For the linear units SR-D various adaptation options, for attaching (or redirecting), for Motors or Gearboxes are available.



i The aluminium profiles are manufactured according to the medium EN 12020-2 standard Straightness = 0.35 mm/m; Max. torsion = 0.35 mm/m; Angular torsion = 0.2 mm/40 mm; Parallelism = 0.2 mm

STRUCTURAL DESIGN



- 1 Drive block with floating bearing
- 2 Gap-type seal of antistatic PU strip (recirculating)
- 3 Ball screw tolerance ISO7 (ISO5 available on request)
- 4 Carriage; with built in Magnets
- 5 Aluminum cover
- 6 Aluminium profile-Hard anodized
- 7 Two integrated Linear Ball Guideways
- 8 Central lubrication port; both sides
- 9 End block with fixed bearing

HOW TO ORDER

	SR 0	200 D	- 0950	- 32	5	0 -	S	0
Series Prefix: SR Size: 0090: 90								
0110: 110 0145: 145 0200: 200								
Series Suffix: ————————————————————————————————————								
Absolute stroke [mm]: (Absolute stroke = Effective stroke + 2	x Safety stroke)						
Ball Screw Dia./Pitch: SR0090 (⊘ 12): 05, 10 SR0110 (⊘ 16): 05, 10, 16 SR0145 (⊘ 20): 05, 10, 20, 50 SR0200 (⊘ 32): 05, 10, 20, 32								
Ball Screw Tolerance: 7: ISO7 5: ISO5								
Ball Screw Journal: 0: Without 1: With (available only for BR0110Z) <i>Note: SR0090 only available with optic</i>	on 0							
Carriage Version: ————————————————————————————————————								
Version: A: Without connection plate, without a B: Without connection plate, with antis	intistatic PU Ga static PU Gap-ty	p-type seal st /pe seal strip,	rip, single car single carriac	riage je				
C: Without connection plate, with corre D: With connection plate, without antis E: With connection plate, with antistat	osion-resistant static PU Gap-ty ic PU Gap-type	protection str ype seal strip, seal strip, sin	ip, single carr single carriag gle carriage	iage ge				
 F: With connection plate, with corrosic G: Without connection plate, without a H: Without connection plate, with antis I: Without connection plate, with corro J: With connection plate, without antis 	on-resistant pro intistatic PU Ga static PU Gap-ty sion-resistant p itatic PU Gap-ty	tection strip, s p-type seal st ype seal strip, protection stri ype seal strip,	single carriago rip, multi-carr multi-carriag p, multi-carriag multi-carriago	e iage e ige e				

K: With connection plate, with antistatic PU Gap-type seal strip, multi-carriage

L: With connection plate, with corrosion-resistant protection strip, multi-carriage

S: Special Version

* Specify the number of carriages and distance between in special notes

General technical data

Linear Unit	Carriage Iength	i Dynamic load capacity	i Dyr	namic mom	ent	For	Max. pe rces	rmissibl	e loads Momer	nts	Moved mass	* Max. length	* Max. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	Lmax [mm]	[mm]
SR-D 90 S	35	4620	125	17	34	2000	4540	125	17	34	0.3	750	665
SR-D 90 L	100	9240	250	300	300	3990	9090	250	297	130	0.5	750	600

* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).



General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic momen	ıt	*		Max. perr	nissible loads	
Unit	version	load capacity				For	ces	Moments		
		C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy[N]	Fpz [N]	Mpx [Nm]	M _{PY} [Nm]	Mpz [Nm]
SP D 00	S2	9240	250	4.6 × A	$4.6 \times A$	3990	9090	250	4.5 imes A	$2.0 \times A$
5R-D 90	L2	18480	500	9.2 × A	9.2 × A	7980	18170	500	$9.0 \times A$	$4.0 \times A$

*A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated by contacting our engineers.



Ball Screw Drive data

i

Linear Unit	Ball screw	Max. rotational speed	1 Max. travel speed	² No load Carriage:	d torque Carriage:	Lead constant	3 repete preci	3 Max. repeteability precision STANIDARD		Max. Dy repeteability precision Imm J standard		Max. Axial load	Max. drive torque	⁴ Min. stroke	1 Max. accele-rati on
	[d×l]	[rev / min]	[m/s]	S [Nm]	L [Nm]	[mm / rev]	standard ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]		
	12 × 5	5900	0.49	0.08 × nc	0.10 × nc	5	± 0.02	± 0.01	5000	5000	4.4 without Keyway	20	20		
3n-D 90	12 × 10	5600	0.97	0.09 × nc	0.11 × nc	10	± 0.02	± 0.01	3800	2540	4.5 without Keyway	30	20		

1 Max. travel speed depends of the length of the linear unit, see diagram for particular size of the linear unit. For travel speed and acceleration over the stated value in the table above or diagrams please contact us.

² The stated values are for strokes (and distances between the carriages A) up to 500mm. No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages

3 For the ball nut with the preload of 2% please contact us

4 For minimum stroke below the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear unit	Mass of linear unit	Planar mom	ent of inertia
	[kg]	ly [cm ⁴]	lz [cm ⁴]
SR-D 90 S	$1.6 + 0.006 \times (Abs. stroke + (nc - 1) \times A) + 0.30 \times (nc - 1)$	12.6	102.6
SR-D 90 L	2.2 + 0.006 × (Abs. stroke + (nc - 1) × A) + 0.50 × (nc - 1)	13.0	102.0

Linear unit	Ball screw	Mass moment of inertia
	[d × l]	[10 ⁻⁵ kg m ²]
	12 × 5	0.32 + 0.002 × (Abs. stroke + (nc - 1) × A) + 0.02 × (nc - 1)
SK-D 90 S	12 × 10	$0.38 + 0.002 \times (Abs. stroke + (nc - 1) \times A) + 0.08 \times (nc - 1)$
	12 × 5	0.43 + 0.002 × (Abs. stroke + (nc - 1) × A) + 0.03 × (nc - 1)
3n-D 90 L	12 × 10	$0.53 + 0.002 \times (Abs. stroke + (nc - 1) \times A) + 0.13 \times (nc - 1)$

* Absolute stroke [mm] A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps. i

Deflection of the linear unit



SR-D 90 LINEAR UNITS

DIMENSIONS



Defining of the linear unit length





CONNECTION PLATE

SR-D 90 S



Maximum travel speed as a function of the profile length (Vmax - L curves)



125 16 <u>40 ^{±0.01}</u> -Ø4 H7 Ø9 Н7 2.1 mm Deep (8x) 10 mm Deep (2x) $30^{\pm 0.01}$ 20^{±0.01} For centering ring CR9 Accessories see on page 116 D ۲ ۲ ⊕ æ ±0.01 Æ 6 ±0.01 \oplus 11 ¢ ŝ ⊕ € ⊕ ₽⊕ 38^{±0.01} 38^{±0.01}

SR-D 90 L

Lubrication nipple DIN 3405D (both sides)

Linear Unit	Plate length [mm]	Weight [kg]	Code
SR-D 90 S	60	0.21	395-103669
SR-D 90 L	125	0.44	395-103668

Mounting elements for mounting the connection plate on the Linear unit are inlcuded.

Mounting the drive

i

- by the MOTOR SIDE DRIVE MSD(Page 112)
- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i Dynamic moment			For	Max. pe ces	rmissible	e loads Momen	its	Moved mass	* Max. length	* Max. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	Lmax [mm]	[mm]
SR-D 110 S	39	19800	650	118	235	4670	9390	310	90	90	0.63	4500	1410
SR-D 110 L	124	39600	1305	1680	1680	13080	18800	620	800	550	1.36	1500	1325
* For longth	a / atraka ava	r the stated value in th	a tabla aba		ontoot up								

You renginely stroke over the stated value in the table above please contact us. Values for max, stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).



General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic momer	nt	*		Max. perr	nissible loads	Mpz [Nm]		
Unit	version	load capacity				For	ces	Moments				
		C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]		
SP D 110	S2	39600	1300	19.8 × A	19.8 × A	12940	18790	620	$9.4 \times A$	6.5 imes A		
Sh-D TIU	L2	79200	2600	39.6 × A	39.6 × A	26100	37600	1240	18.8 × A	13.0 × A		

* A - Distance between carriages [mm]. More info on following pages.

Presented values are for informational purposes only. Exact values can be calculated

i



Ball Screw Drive data

by contacting a sales engineer.

Linear Unit	Ball screw	Max. rotational	1 Max. travel speed	² No load	d torque	Lead constant	3 Ma repete pr <u>eci</u>	ıx. ability sion	Dynamic load capacity	Max. Axial load	Max. drive torque	⁴ Min. stroke	1 Max. accele-rati on
	[d × l]	[rev / min]	[m/s]	S [Nm]	L [Nm]	[mm / rev]	t m standard ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]
CD D 110	16 × 5	4200	0.35	0.17 × nc	0.20 × nc	5	± 0.02	± 0.01	13150	8700	5.5 with Keyway 7.7 without Keyway	40	20
3N-D 110	16 × 10	4200	0.70	0.18 imes nc	$0.21 \times nc$	10	± 0.02	± 0.01	11550	6730	5.5 with Keyway	40	20
	16 × 16		1.12	$0.23 \times \text{nc}$	0.26 imes nc	16	± 0.02	± 0.01	8170	4200	11.9 without Keyway		

1 Max. travel speed depends of the length of the linear unit. see diagram for particular size of the linear unit. For travel speed and acceleration over the stated value in the table above or diagrams please contact us.

² The stated values are for strokes (and distances between the carriages A) up to 500mm.

No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages

³ For the ball nut with the preload of 2% please contact us⁴ For minimum stroke below the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear unit	Mass of linear unit	Planar mome	ent of inertia
	[kg]	ly [cm⁴]	lz [cm ⁴]
SR-D 110 S	3.3 + 0.008 × (Abs. stroke + (nc - 1) × A) + 0.63 × (nc - 1)	20.1	106.0
SR-D 110 L	4.6 + 0.008 × (Abs. stroke + (nc - 1) × A) + 1.36 × (nc - 1)	29.1	190.0

Linear unit	Ball screw	Mass moment of inertia
	[d × l]	[10 ⁻⁵ kg m ²]
	16 × 5	0.70 + 0.005 × (Abs. stroke + (nc - 1) × A) + 0.04 × (nc - 1)
SR-D 110 S	16 × 10	$0.82 + 0.005 \times (Abs. stroke + (nc - 1) \times A) + 0.16 \times (nc - 1)$
	16 × 16	1.07 + 0.005 × (Abs. stroke + (nc - 1) × A) + 0.41 × (nc - 1)
	16 × 5	1.19 + 0.005 × (Abs. stroke + (nc - 1) × A) + 0.09 × (nc - 1)
SR-D 110 L	16 × 10	$1.45 + 0.005 \times (Abs. stroke + (nc - 1) \times A) + 0.34 \times (nc - 1)$
	16 × 16	1.99 + 0.005 × (Abs. stroke + (nc - 1) × A) + 0.88 × (nc - 1)

i

* Absolute stroke [mm]

A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit



SR-D 110 LINEAR UNITS

DIMENSIONS



Defining of the linear unit length





CONNECTION PLATE

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SR-D 110

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Lubrication nipple DIN 3405D (both sides)

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SR-D 110 L



Linear Unit	Plate length [mm]	Weight [kg]	Code
SR-D 110 S	60	0.37	395- 000103671
SR-D 110 L	155	0.74	395- 000103670

Mounting elements for mounting the connection plate on the Linear unit are inlcuded.

Mounting the drive

i

- by the MOTOR SIDE DRIVE MSD (Page 112)
- by the MOTOR ADAPTER WITH COUPLING (Page 120)

Available on request.



Maximum travel speed as a function of the profile length (Vmax - L curves)



General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i Dynamic moment			For	Max. pe ces	rmissible	e loads Momen	its	Moved mass	* Max. length	* Max. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	Lmax [mm]	[mm]
SR-D 145 S	49	34200	1500	260	520	8930	15320	674	260	180	1.19	1000	1690
SR-D 145 L	149	68400	3005	3420	3420	17870	30680	1350	1700	893	2.61	1800	1590
* For length	s / stroke over	r the stated value in th	e table abo	ve please c	ontact us.								

Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).



General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic momer	nt	*		Max. perr	nissible loads	
Unit	version	load capacity					ces	Moments		
		C[N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]
	S2	68400	3000	34.2 × A	34.2 × A	17870	30640	1350	15.3 × A	8.9 × A
3n-D 145	L2	136800	6000	68.4 × A	68.4 × A	35700	61300	2700	30.6 × A	17.8 × A

* A - Distance between carriages [mm]. More info on following pages.

i Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Ball Screw Drive data

Linear Unit	Ball screw	Max. rotational	1 Max. travel speed	² No load	d torque	Lead constant	3 Ma repete	ıx. ability	Dynamic load capacity	Max. Axial load	Max. drive torque	⁴ Min.	1 Max. accele-rati
onne		speed		Carriage:	Carriage:		precision [mm] STANDARD		BS			ouono	on
	[d × l]	[rev / min]	[m / s]	[Nm]	[Nm]	[mm / rev]	ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]
	20 × 5	0000	0.28	0.30 × nc	0.35 × nc	5	± 0.02	± 0.01	14800	14800	11.9 with Keyway 13.0 without Keyway		
SR-D 145	20 × 10	3300	0.55	$0.32 \times nc$	$0.37 \times nc$	10	± 0.02	± 0.01	15900	13850	11.9	55	20
2	20 × 20		1.10	0.45 imes nc	0.50 imes nc	20	± 0.02	± 0.01	16250	6930	with Keyway 24.5	,	
	20 × 50	3000	2.50	0.80 imes nc	0.85 imes nc	50	± 0.02	± 0.01	13000	2770	without Keyway		

1 Max. travel speed depends of the length of the linear unit, see diagram for particular size of the linear unit. For travel speed and acceleration over the stated value in the table above or diagrams please contact us.

² The stated values are for strokes (and distances between the carriages A) up to 500mm.

No Load Torque value increases with stroke (and with A) elongation.

nc - Number of carriages

 $3\,For$ the ball nut with the preload of 2% please contact us

4 For minimum stroke below the stated value in the table above please contact us.

Mass and mass moment of inertia

Linear unit	Mass of linear unit	Planar moment of inertia			
	[kg]	ly [cm⁴]	lz [cm ⁴]		
SR-D 145 S	$5.7 + 0.015 \times (Abs. stroke + (nc - 1) \times A) + 1.19 \times (nc - 1)$	95.2	602.2		
SR-D 145 L	8.4 + 0.015 × (Abs. stroke + (nc - 1) × A) + 2.61 × (nc - 1)	05.5	002.3		

Linear unit	Ball screw	Mass moment of inertia
	[d × l]	[10 ⁻⁵ kg m ²]
	20 × 5	3.04 + 0.013 × (Abs. stroke + (nc - 1) × A) + 0.08 × (nc - 1)
	20 × 10	$3.27 + 0.013 \times (Abs. stroke + (nc - 1) \times A) + 0.30 \times (nc - 1)$
SR-D 145 S	20 × 20	4.17 + 0.013 × (Abs. stroke + (nc - 1) × A) + 1.21 × (nc - 1)
	20 × 50	10.50 + 0.013 × (Abs. stroke + (nc - 1) × A) + 7.54 × (nc - 1)
	20 × 5	$4.43 + 0.013 \times (Abs. stroke + (nc - 1) \times A) + 0.17 \times (nc - 1)$
	20 × 10	$4.92 + 0.013 \times (Abs. stroke + (nc - 1) \times A) + 0.66 \times (nc - 1)$
3R-D 143 L	20 × 20	$6.91 + 0.013 \times (Abs. stroke + (nc - 1) \times A) + 2.64 \times (nc - 1)$
	20×50	$20.79 + 0.013 \times (Abs. stroke + (nc - 1) \times A) + 16.53 \times (nc - 1)$

* Absolute stroke [mm]

A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages

Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit





SR-D 145 LINEAR UNITS

DIMENSIONS



Defining of the linear unit length



106



SR-D 145 L



Lubrication nipple DIN 3405D (both sides)

Linear Unit	Plate length [mm]	Weight [kg]	Code
SR-D 145 S	80	0.78	395- 000103673
SR-D 145 L	190	1.54	395- 000103672

Mounting elements for mounting the connection plate on the Linear unit are inlcuded.

i



SR-D 145



Mounting the drive

- by the MOTOR SIDE DRIVE - MSD (Page 112) - by the MOTOR ADAPTER WITH COUPLING (Page 120)

ADAPTER WITH COOPLING (Page 120)

Available on request.



In order to improve the products in this catalog the specifications are subject to change without notice.

General technical data

Linear Unit	Carriage length	i Dynamic load capacity	i Dynamic moment			Max. permissible loads Forces Moments					Moved mass	* Max. length	* Max. stroke
	Lv [mm]	C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	[kg]	Lmax [mm]	[mm]
SR-D 200 S	80	49600	3220	450	900	10000	24610	1600	450	308	3.11	0000	2000
SR-D 200 L	255	99200	6445	8680	8680	20000	51540	3350	4550	1750	6.21	2200	1825

* For lengths / stroke over the stated value in the table above please contact us. Values for max. stroke are not valid for multiple carriages (equation of defining the linear unit length for particular size of the linear unit needs to be used).



General technical data for double carriage

Linear	Carriage	Dynamic	*	Dynamic momer	nt	* Max. permissible loads					
Unit	version	ion load capacity		For	ces	Moments					
		C [N]	Mx [Nm]	My [Nm]	Mz [Nm]	Fpy [N]	Fpz [N]	Mpx [Nm]	Mpy [Nm]	Mpz [Nm]	
SP D 200	S2	99200	6440	49.6 × A	49.6 × A	20000	49230	3200	$24.6 \times A$	10.0 × A	
SR-D 200	L2	198400	12890	99.2 × A	99.2 × A	40000	103000	6700	51.5 × A	20.0 × A	

* A - Distance between carriages [mm]. More info on following pages.



Presented values are for informational purposes only. Exact values can be calculated by contacting a sales engineer.



Ball Screw Drive data

Linear	Ball screw	Max.	k. Max. travel speed	² No load torque		Lead constant	3 Max. repeteability		Dynamic load capacity	Max.	Max. drive torque	⁴ Min.	1 Max. accele-rati
Onit		speed		Carriage:	Carriage:			ision im J BS		Axiai ioau		SLIUKE	on
	[d × l]	[rev / min]	[m / s]	S [Nm]	[Nm]	[mm / rev]	ISO7	ISO5	Ca [N]	Fx [N]	Ma [Nm]	[mm]	[m/s²]
SR-D 200	32 × 5	2150	0.18	0.60 × nc	0.70 × nc	5	± 0.02	± 0.01	18850	18850	16.7 with Keyway 16.7 without Keyway	05	20
	32 × 10		0.50	$0.70 \times nc$	$0.80 \times nc$	10	± 0.02	± 0.01	37000	29600	27.3	65	
	32 × 20	3000	1.00	$0.75 \times nc$	$0.85 \times nc$	20	± 0.02	± 0.01	22950	14800	with Keyway 52.3		
	32 × 32		1.60	0.80 imes nc	0.90 imes nc	32	+ 0.02	+ 0.01	15550	9240	without Keyway	70	

1 Max. travel speed depends of the length of the linear unit, see diagram for particular size of the linear unit.

For travel speed and acceleration over the stated value in the table above or diagrams please contact us. ² The stated values are for strokes (and distances between the carriages A) up to 500mm.

No Load Torque value increases with stroke (and with A) elongation nc - Number of carriages

3 For the ball nut with the preload of 2% please contact us

4 For minimum stroke below the stated value in the table above please contact us.
TECHNICAL DATA

Mass and mass moment of inertia

Linear unit	Mass of linear unit	Planar mom	ent of inertia
	[kg]	ly [cm ⁴]	lz [cm ⁴]
SR-D 200 S	$15.4 + 0.031 \times (Abs. stroke + (nc - 1) \times A) + 3.11 \times (nc - 1)$	417 4	2007.2
SR-D 200 L	23.8 + 0.031 × (Abs. stroke + (nc - 1) × A) + 6.21 × (nc - 1)	417.4	3007.3

Linear unit	Ball screw	Mass moment of inertia
	[d × l]	[10 ⁻⁵ kg m ²]
	32 × 5	21.17 + 0.069 × (Abs. stroke + (nc - 1) × A) + 0.20 × (nc - 1)
	32 × 10	$21.76 + 0.069 \times (Abs. stroke + (nc - 1) \times A) + 0.79 \times (nc - 1)$
5R-D 200 5	32 × 20	24.12 + 0.069 × (Abs. stroke + (nc - 1) × A) + 3.15 × (nc - 1)
	32 × 32	29.04 + 0.069 × (Abs. stroke + (nc - 1) × A) + 8.07 × (nc - 1)
	32 × 5	33.41 + 0.069 × (Abs. stroke + (nc - 1) × A) + 0.39 × (nc - 1)
	32 × 10	$34.59 + 0.069 \times (Abs. stroke + (nc - 1) \times A) + 1.57 \times (nc - 1)$
3R-D 200 L	32 × 20	39.31 + 0.069 × (Abs. stroke + (nc - 1) × A) + 6.29 × (nc - 1)
	32 × 32	$49.12 + 0.069 \times (Abs. stroke + (nc - 1) \times A) + 16.11 \times (nc - 1)$

* Absolute stroke [mm]

A - Distance between carriages [mm]. More info on following pages. nc - Number of carriages Mass calculation doesn't include mass of motor, reduction gear, switches and clamps.

Deflection of the linear unit





DIMENSIONS



DIMENSIONS



CONNECTION PLATE

SR-D 200 S



SR-D 200 L

Lubrication nipple DIN 3405D (both sides)

Linear Unit	Plate length [mm]	Weight [kg]	Code
SR-D 200 S	190	2.32	395- 000103675
SR-D 200 L	305	3.75	395- 000103674

Mounting elements for mounting the connection plate on the Linear unit are inlcuded.

Please consider our advice in our Maintenance- and assembly instructions

Mounting the drive

i

- by the MOTOR SIDE DRIVE MSD(Page 112)
- by the MOTOR ADAPTER WITH COUPLING (Page 120)

1 Available on request.



Lubrication nipple DIN 3405D (both sides) —





Slot nut More info on page 117

Maximum travel speed as a function of the profile length (Vmax - L curves)



SR-D/SR-S MOTOR SIDE DRIVE UNIT LINEAR UNITS

STRUCTURAL DESIGN



- 4- Toothed belt
 5- Belt tensioning system (elongation and frequency of belt span provided with
- delivery of unit) 6 Motor
- 7 Linear unit SR-D / SR-S
- The linear unit must be executed with drive journal without keyway, so that the MSD belt drive can be mounted on it. **i**



D Down

See next page

TECHNICAL DATA AND DIMENSIONS





R Right

L Left

U Up



Keyway





TECHNICAL DATA AND DIMENSIONS

Technical data

Linear Unit	Туре	Gear	Max. drive	** Max.	Mass moment of	Mass				Mot	or size lim	its [m	m]		
		ratio	torque (linear unit)	radial load on shaft	inertia	***	ØВ	øс	*M		L1		ø	D	
					6 , 2 ,	<i>.</i>	max	max	max	m	in L	max	Clamping set	Keyv	vay
		1	[Nm]	[N]	[10 kg m]	[kg]				Clamping set	Keyway		max	min	max
SR0040S	1A	1	1.3	60	4.6	0.5	60	36	4		20	32	8	>8	12
51100405	1B	1.5	1.3	60	5.4	0.5	00	30	4		20	52	8	-	-
CD0040C	2A	1	3	80	45	0.8	00	50			25	20	19	-	-
SR00405	2B	1.5	3	80	31	0.7	80	52	4		25	39	10	>10	14
CRAAAD	1A	1	2.7	90	75	0.8	70				05	00	19	-	-
3000900	1B	1.5	2.7	90	45	0.7	70	0 -	4		25	39	10	>10	14
SR0110D	1A	1	5	175	70	0.8	70				25	20	19	-	-
SR0065S	1B	1.5	5	175	45	0.8	70	-	4		25	39	10	>10	14
SR0110D	2A	1	9	245	210	1.5	100		4	****	20	40	22	-	-
SR0065S	2B	1.5	11	235	330	1.5	100	-	4		30	49	19	>19	28
SR0145D	1A	1	13	350	210	1.5	100		4		20	40	22	-	-
SR0080S	1B	1.5	19	410	330	1.6	100		4		30	43	19	>19	28
SR0145D	2A	1	19	410	550	3.0	100				05	50	35	-	-
SR0080S	2B	2	24	375	860	2.9	130	-	4		35	59	19	>19	28
SR0200D	1A	1	25	500	640	3.8	100				25	50	35	-	-
SR0110S	1B	2	25	400	960	3.6	130	130 -			35	59	19	>19	28

(max. drive speed: 3000 1/min; No load torque: approx. 0.5 Nm)

* For a bigger value an additonal adapter plate is used. For the case of SR0040S a thicker plate may be used.

** This is the load which is linearly dependent on the max. drive torque and is generated by the correct pretension of the belt. This load needs to be reduced in accordance with the capabilities of the motor.

*** This is an average value. It could differ depending to the motor dimensions.

**** Minimum dimension L1 depends on the size of particular clamping set. Values can be found in the table on page 114.

Dimensions

Linear Unit	Туре	Gear ratio		Dimensions [mm]							
		i	E (± 0.5)		F	G	G2	К	Ν		
SP0040S	1A	1	58.5	110	50	20	22	26	C *		
3000403	1B	1.5	59	113	52	39	33	20	0 "		
600406	2A	1	65	405		40	00	0.1	0 *		
SR00405	2B	1.5	64.5	135	68	42	30	31	8 ^		
SBOOOD	1A	1	100	170	70	41		21	2		
3000900	1B	1.5	102	179	70	41	-	31	2		
SR0110D	1A	1	100	179	70			0.1			
SR0065S	1B	1.5	112	190	70	41	-	31	2		
SR0110D	2A	1	145	250	00	E 1		40	2		
SR0065S	2B	1.5	139	250	90	51	-	43	2		
SR0145D	1A	1	145	250	00	E 1		40	2		
SR0080S	1B	1.5	180	282	90	51	-	43	2		
SR0145D	2A	1	160	007	100			50			
SR0080S	2B	2	158	297	120	61	-	56	2.5		
SR0200D	1A	1	268	100	100	0.1		50	0.5		
SR0110S	1B	2	267	403	120	61	-	56	2.5		

* This is a standard value. It could differ depending to the motor dimensions M and L1.

TECHNICAL DATA AND DIMENSIONS

Minimum dimension L1 [mm] depends on the motor shafts diameter ${\it \varnothing D}$

Linear Unit	Туре	Gear ratio			ØD [mm]																							
		i	4	5	6	6.35	7	8	9	9.53	10	11	12	14	15	16	17	18	19	20	22	24	25	25.4	28	30	32	35
C D 00 40 C	1A	1	17	17	17	17	17	17	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
5K00405	1B	1.5	17	17	17	17	20	20	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
SBUUADS	2A	1	-	-	17	17	17	17	18	18	18	18	18	22	22	22	25	25	25	-	-	-	-	-	-	-	-	-
31100403	2B	1.5	-	-	17	17	17	17	18	18	18	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
SBOOOD	1A	1	-	-	23	23	23	23	24	24	24	24	24	28	28	28	31	31	31	-	-	-	-	-	-	-	-	-
5K0090D	1B	1.5	-	-	23	23	23	23	24	24	24	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
SR0110D	1A	1	-	-	23	23	23	23	24	24	24	24	24	28	28	28	31	31	31	-	-	-	-	-	-	-	-	-
SR0065S	1B	1.5	-	-	23	23	23	23	24	24	24	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
SR0110D	2A	1	-	-	-	-	-	23	24	24	24	24	24	28	28	28	31	31	31	31	31	-	-	-	-	-	-	-
SR0065S	2B	1.5	-	-	-	-	23	23	24	24	24	24	24	28	28	28	31	31	31	-	-	-	-	-	-	-	-	-
SR0145D	1A	1	-	-	-	-	-	-	24	24	24	24	24	28	28	28	31	31	31	31	31	-	-	-	-	-	-	-
SR0080S	1B	1.5	-	-	-	-	-	-	24	24	24	24	24	28	28	28	31	31	31	-	-	-	-	-	-	-	-	-
SR0145D	2A	1	-	-	-	-	-	-	-	-	-	-	29	33	33	33	36	36	36	36	36	40	40	40	40	40	40	43
SR0080S	2B	2	-	-	-	-	-	-	29	29	29	29	29	33	33	33	36	36	36	-	-	-	-	-	-	-	-	-
SR0200D	1A	1	-	-	-	-	-	-	-	-	-	-	29	33	33	33	36	36	36	36	36	40	40	40	40	40	40	43
SR0110S	1B	2	-	-	-	-	-	-	29	29	29	29	29	33	33	33	36	36	36	-	-	-	-	-	-	-	-	-

FIXING SYSTEM



Recommended number of clamping fixtures: For T1 is recommended 6 pcs. per meter on each side. for T2 is recommended 3 pcs. per meter on each side.

CENTERING RINGS







CR 9





CR 7 / 9







CR 12



E-E

M8

Ø12 k6

-0.7 X 45°

4_0.10

0.3 X 45°



F

1

0.3 X 45°



Туре	Compatible with	Code
CR 7	BR-S/BT-S/BR-Z/SR-S: 40, 65	395- 000023332
CR 9	BR-S/BT-S /SR-S/BR-Z: 80,110 SR-D/BR-D: 90, 110	395- 000023331
CR 7/9	BR-S/BT-S/SR-S/BR-Z/ SR-D/BR-D: 90, 110	395- 000075114
CR 9/12	BR-S/BT-S /SR-S/BR-Z: 80,110 SR-D/BR-D: 90, 110, 145	395- 000048885
CR 12	SR-D/BR-D: 145	395- 000049049
CR 16	SR-D/BR-D: 200	395- 000053023

SLOT NUTS



M10

Ø16 k6



DIN557



* - deviating CODE

LINEA	LINEAR UNITS - PROFILE		DIN562						* - deviating CODE				
CODE	NUT TYPE	BR-S/ BT-S 40	SR-S 40	BR-S/BT-S/ SR-S/BR-Z 65	BR-S/BT-S/ SR-S/BR-Z 80	BR-S/BT-S/ SR-S /BR-Z 110	BR-E 40	SR-D/ BR-D 90	SR-D/ BR-D 110	SR-D/ BR-D 145	SR-D/ BR-D 200		
395- 000041609	DIN562 - M2.5		Х					Х	Х	Х			
395- 000040682	DIN562 - M4	X - *395- 000057017		Х	Х			Х			Х		
395- 000040768	DIN562 - M5								х	Х			
395- 000040769	DIN557 - M5			Х	Х								
395- 000044451	DIN557 - M8					х					Х		
395- 000005746	Slot Nut M6						Х						
395- 000005551	Slot Nut T-10-M8										Х		
395- 000005552	Slot Nut T-10-M6										Х		
395- 000005553	Slot Nut T-10-M5										Х		
395- 000005570	Slot Nut T-10-M8 L=90										Х		

LINEAR UNITS - CONNECTION PLATES

CODE	NUT TYPE	SR-D/ BR-D 200	CODE	NUT TYPE	SR-D/ BR-D 145	CODE	NUT TYPE	SR-D/ BR-D 110	SR-D/ BR-D 90
395- 000005551	Slot Nut T-10-M8	Х	395- 000005704	Slot Nut 8LM4	Х	395- 000048887	Slot Nut 6LM4	Х	Х
395- 000005552	Slot Nut T-10-M6	Х	395- 000005703	Slot Nut 8LM5	Х	395- 000048888	Slot Nut 6LM5	Х	Х
395- 000005553	Slot Nut T-10-M5	Х	395- 000005702	Slot Nut 8LM6	Х				
395- 000005570	Slot Nut T-10-M8 L =90	Х	395- 000005701	Slot Nut 8LM8	Х				

MAGNETIC FIELD SENSORS

BR-S / BT-S / SR-S



- 1 Magnetic field sensor 2 Sensor holder

SR-D / BR-D 0 6 2 1

Mounting of Magnetic field sensor on SR-D and BR-D series requires a HOM sensor holder.

For SR-S 40 a HOM sensor holder is also needed. For SR-D/BR-D 200 a HOM sensor holder is not needed.

SMT-65TP-K N0/NC	Code	Туре	Compatibility	
	395- 000043851	HOM Sensor holder	SR-S 40, SR-D90, SR-D110, SR-D145, BR-D90, BR-D110, BR-D145	
	395- 000074073	SMT-65TP-K NC	BR-S/BT-S/SR-S/BR-SZ:40,65,80, 110 SR-D/BR-D: 200	I BUT
	395- 000077075	SMT-65TP-K NC + HOM	SR-S 40, SR-D90, SR-D110, SR-D145, BR-D90, BR-D110, BR-D145	
28 300±20	395- 000074074	SMT-65TP-K NO	BR-S/BT-S/SR-S/BR-SZ:40,65,80, 110 SR-D/BR-D: 200	I BUT
	395- 000077076	SMT-65TP-K NO + HOM	SR-S 40, SR-D90, SR-D110, SR-D145, BR-D90, BR-D110, BR-D145	
Extension cable with connector	395- 00008146	Extension Cable	length 2m - Straight connector	O Drown
24.1 (REF) CABLE (3mm)	395- 00008147	Extension Cable	length 5m - Straight connector	a Drom
	395- 00009017	Extension Cable	length 2m - Angeled connector	ø
	395-	Extension Cable	length 5m - Angeled connector	Ø

TECHNICAL DATA	SMT-65TP-K NC	SMT-65TP-K NO
Sensor Type	GMR sensor	GMR sensor
Switching function	NC	NO
Output	PNP	PNP
Operating voltage	10 ~ 28 V DC	10 ~ 28 V DC
Switching Current	200 mA max.	200 mA max.
Power rating	5.5 W max.	5.5 W max.
Voltage Drop	1.5 V / 200mA max.	1.5 V / 200 mA max.
Current Consumption	10 mA / 24 V max.	10 mA / 24 V max.
Switching Frequency	1000 Hz	1000 Hz
Ambient temperature	-10 ~ +70°C	-10 ~ +70°C
Shock/Vibration	50 G / 9 G	50 G / 9 G
Protection class	IP 67	IP 67
LED indicator	yellow	Yellow
Electrical connection	M8, 3-pin	M8, 3-pin
Cable material length	PU - 0.3 m	PU - 0.3 m
Extension cable	Energy chain compliant	Energy chain compliant

Mounting and using the Induction and Mechanical

switch. can be done only if the SR-D and BR-D series Linear Units are delivered with Connection

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plates.

CTV10

BR-S / BT-S / SR-S

MS- Mechanical switch

TECHNICAL DATA



SR-D / BR-D

10:

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	ORDERI	NG CODES	BR-S/ BT-S 40	BR-Z 40	SR-S 40	BR-S/BT-S/SR-S 65; BR-Z 65/80	BR-S/BT-S/ SR-S 80	BR-S/BT-S/ SR-S 110	BR-Z 110	BR-E 40	SR-D/ BR-D 90	SR-D/ BR-D 110	SR-D/ BR-D 145	SR-D/ BR-D 200
	+ 2× 🗍	Activation block with fixing screws	395- 0000 43243	395- 0000 52022	395- 0000 43243	395-000043247	395-000043256	395- 0000 47827	395- 0000 63702	395- 0000 49030	395- 0000 49032	395- 0000 49031	395- 0000 40652	395- 0000 40652
		Mechanical switch only					3	95-0000479	921					
2×🗄 +	+ 2× + 2×	Mechanical switch with	395-000040683		395- 0000 104970	395-000040687	395-000040689	395- 0000 47826	395- 0000 63703	395- 0000 49035	395- 0000 49034	395- 0000 49033	395- 0000 47939	395- 0000 53055

IS- Inductive switch

TECHNICAL DATA PNP Sensor Type 27.8 NC / NO Switching function 6 2.85 10 ~ 30 V DC Rated voltage 16 6 6 150 mA max. Switching Current -25°C ...+70°C Ambient temperature M8 Switching Frequency 800 Hz max. (\bigcirc) $(\bigcirc$ Voltage Drop 3.5 V Protection class IP 67 M8. 3-pin Electrical connection Extension cable with connector Energy chain compliant - bending radius = 75 mm Extension cable 32.1 (REF) CABLE (3mm) Cable material-length PU 24.1 (REF) m Cable length 2m / 5m Cable length M8. 3-pin Straight or Angeled connector Ø9 BR-S/BT-S SR-S80 R-E 4 **ORDERING CODES** R-40 R-3 40 SR-D/ 3R-D 90 SR-D/ R-D 11(SR-D/ 3R-D 145 SR-D/ 3R-D 20 SR-395-0000 52022 395-0000 43243 395-0000 63702 395-0000 49030 395-0000 49032 395-0000 40652 395-0000 4903 Activation block with fixing screws 395-0000 395-0000 40652 + 2× 395-000043247 395-000043256 0000 47827 PNP NO Inductive switch 395-000040671 395-0000 45105 395-0000 49039 395-0000 49038 395-0000 48058 395-0000 53054 Ind. switch with mounting elements 395-0000 10496 395-0000 48047 395-0000 63705 2×8+ +2×||+ PNP NO 395-000040680 395-000048026 395-000043233 PNP NC Inductive switch only 395-000043570 Ind. switch with mounting elements 395-0000 45103 395-0000 47989 395-0000 63704 PNP NC 0000 10496 0000 0000 53052 2×8+ +2×||+ 395-000040685 395-000047848 0000 49037 0000 47850 395-000048851 Extension Cable length 2m - Straight connector 395-000008146 on Da Extension Cable length 5m - Straight connector 395-000008147 395-000009017 Extension Cable length 2m - Angeled connector đ) 395-000009019 Extension Cable length 5m - Angeled connector

In order to improve the products in this catalog the specifications are subject to change without notice.

MOTOR ADAPTER WITH COUPLING

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*The values of nominal TKN** and max. TKmax** transmissible torque in the upper table are valid for coupling with Keyway! **for legend see page 121

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In order to improve the products in this catalog the specifications are subject to change without notice.

Size	Recommended coupling bore diam. and Transmissible Torque [Nm] - valid for shaft tolerances k6 without Keyway																								
	Ø4	Ø5	Ø6	Ø7	Ø8	Ø9	Ø10	Ø11	Ø12	Ø14	Ø15	Ø16	Ø19	Ø20	Ø22	Ø24	Ø25	Ø28	Ø30	Ø32	Ø35	Ø38	Ø40	Ø42	Ø45
7	0.7	0.8	1.0	1.1																					
9	1.1	1.4	1.7	1.9	2.2	2.5	2.8																		
14			2.5	2.9	3.3	3.7	4.1	4.6	5.0	5.8	6.2	6.6													
19/24							23	25	27	32	34	36	43	45											
24/28							23	25	27	32	34	36	43	45	50	54	57	63							
28/38										58	62	66	79	83	91	100	104	116	124	133	145				
38/45													79	83	91	100	104	116	124	133	145	158	166	174	187
Ms - Scr W - Wei J - Coup nmax - I TKN - Co Tkmay -	Ms - Screw tightening torque N - Weight J - Coupling moment of inertia 1max - Maximum rpm TKN - Coupling nominal torque Tkmax - Coupling nominal torque												N K r N N	m g gm ² nin ⁻¹ m											

The operating temperature range for the coupling is between -30 and +90°C

SYNCHRONIZATION SHAFT OSI



The maximum transmittable torque of the clamping hub depends on the bore diameter (see the upper table on page 121). i





Size	e Internal hub		C⊤ [Nm/rad]	E [mm]	H [mm]	Ød _min	Ød max	M [mm]	N [mm]	S [mm]	L [mm]	Lw min	Lt (mm)	dR x thickness	Weight [kg]	Moment of inertia [10 ⁻⁶ kg * m²]
	Ms [Nm]	M⊤ [Nm]				[mm]	[mm]					[mm]		[mm]		
14	1.34	6	59	30	11	4	16	13	10	1.5	35	48		14 x 2.0	0.072 + 0.00021 * Lw	10.4 + 0.0076 * Lw
19/24	10	34	314	40	25	6	20	16	12	2	66	82	est	20 x 3.0	0.284 + 0.00044 * Lw	72.4 + 0.0324 * Lw
24/28	10	45	596	55	30	8	28	18	14	2	78	96	requ	25 x 2.5	0.624 + 0.00048 * Lw	300 + 0.0614 * Lw
28/38	25	105	2868	65	35	10	38	20	15	2.5	90	110	uo	35 x 5.0	0.960 + 0.00128 * Lw	656 + 0.2954 * Lw
38/45	25	123	4521	80	45	12	45	24	18	3	114	138		40 x 5.0	1.760 + 0.00149 * Lw	1862 + 0.4656 * Lw

Nm

Nm Nm/rad

MS - Screw tightening torque







For longer distances Bearing Supports needed, please contact us.

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SYNCHRONISATION SHAFT OSR





The maximum transmittable torque of the clamping hub depends on the bore diameter (see the upper table on page 8.025.0).

Size	d min [mm]	d max [mm]	Ms [Nm]	M⊤ [Nm]	C⊤ [Nm/rad]	E (mm)	H [mm]	l [mm]	L [mm]	M [mm]	Lw min [mm]	Lt [mm]	D [mm]	t [mm]	e [mm]	dR [mm]	Weight [kg]	Moment of inertia [10 ^{.6} kg * m ²]
19	10	20	10	39	1630	40	25	13	53.5	16	82	÷	47	12	15	36	0.30 + 0.00058 * Lw	66.0 + 0.1679 * Lw
24	10	28	10	53	3980	55	30	16	63	18	96	sənb	57	14	20.8	45	0.62 + 0.00091 * Lw	242 + 0.4099 * Lw
28	14	35	25	137	7494	65	35	20	67	20	110	n rec	73	15	25	55	0.98 + 0.00112 * Lw	572 + 0.7717 * Lw
38	15	45	25	180	14540	80	45	25	83.5	24	138	ō	84	20	30	68	1.75 + 0.00140 * Lw	1522 + 1.4975 * Lw



Nm Nm Nm/rad



INSTALLATION

The overall length Lt is best determined as the distance between shaft ends - length Lw plus 2x dimension H.



SELECTION DIAGRAM

Ideal execution for long distance shat connections. Torque transmission is zero backlash. Designed for lengths up to 4m without bearing support (depending on rotation speed).

Standard lenghts available till 3m, for longer lengths please contact us.



X-Y CONNECTION ELEMENTS

X- Axis BR-S, BT-S, SR-S, BR-E, SR-D = 0° Y Axis = 0°



X-Axis	Y-Axis												
	BR-S, BT-S, SR-S 40	BR-S, BT-S, SR-S 65	BR-S, BT-S, SR-S 80	BR-S, BT-S, SR-S 110	BR-E 40	SR-D, BR-D 90	SR-D, BR-D 110	SR-D, BR-D 145	SR-D, BR-D 200				
BR-S, BT-S, SR-S 40	CP M40 0 M40 0	CP M40 0 M65 0			CP M40 0 E40 0	CP M40 0 C90 0							
BR-S, BT-S, SR-S 65	CP M65 0 M40 0	CP M65 0 M65 0	CP M65 0 M80 0		CP M65 0 E40 0	CP M65 0 C90 0	CP M65 0 C110 0						
BR-S, BT-S, SR-S 80		CP M80 0 M65 0	CP M80 0 M80 0	CP M80 0 M110 0		CP M80 0 C90 0	CP M80 0 C110 0	CP M80 0 C145 0					
BR-S, BT-S 110		CP M110 0 M65 0	CP M110 0 M80 0	CP M110 0 M110 0			CP M110 0 C110 0	CP M110 0 C145 0	CP M110 0 C200 0				
BR-E 40	CP E40 0 M40 0	CP E40 0 M65 0	CP E40 0 M80 0		CP E40 0 E40 0	CP E40 0 C90 0	CP E40 0 C110 0						
SR-D, BR-D 90	CP C90 0 M40 0	CP C90 0 M65 0				CP C90 0 C90 0	CP C90 0 C110 0						
SR-D, BR-D 110	CP C110 0 M40 0	CP C110 0 M65 0	CP C110 0 M80 0			CP C110 0 C90 0	CP C110 0 C110 0	CP C110 0 C145 0					
SR-D, BR-D 145		CP C145 0 M65 0	CP C145 0 M80 0	CP C145 0 M110 0		CP C145 0 C90 0	CP C145 0 C110 0	CP C145 0 C145 0					
SR-D, BR-D 200			CP C200 0 M80 0	CP C200 0 M110 0			CP C200 0 C110 0	CP C200 0 C145 0	CP C200 0 C200 0				

X- Axis BR-S, BT-S, SR-S, BR-E, SR-D = 0° Y Axis = 90°



X-Axis					Y-Axis				
	BR-S, BT-S, SR-S 40	BR-S, BT-S, SR-S 65	BR-S, BT-S, SR-S 80	BR-S, BT-S, SR-S 110	BR-E 40	SR-D, BR-D 90	SR-D, BR-D 110	SR-D, BR-D 145	SR-D, BR-D 200
BR-S, BT-S, SR-S 40	CP M40 0 M40 90	CP M40 0 M65 90			CP M40 0 E40 90	CP M40 0 C90 90			
BR-S, BT-S, SR-S 65	CP M65 0 M40 90	CP M65 0 M65 90	CP M65 0 M80 90			CP M65 0 C90 90	CP M65 0 C110 90		
BR-S, BT-S, SR-S 80		CP M80 0 M65 90	CP M80 0 M80 90	CP M80 0 M110 90		CP M80 0 C90 90	CP M80 0 C110 90	CP M80 0 C145 90	
BR-S, BT-S 110		CP M110 0 M65 90	CP M110 0 M80 90	CP M110 0 M110 90			CP M110 0 C110 90	CP M110 0 C145 90	CP M110 0 C200 90
BR-E 40	CP E40 0 M40 90	CP E40 0 M65 90	CP E40 0 M80 90		CP E40 0 E40 90	CP E40 0 C90 90	CP E40 0 C110 90		
SR-D, BR-D 90	CP C90 0 M40 90	CP C90 0 M65 90				CP C90 0 C90 90			
SR-D, BR-D 110	CP C110 0 M40 90	CP C110 0 M65 90	CP C110 0 M80 90			CP C110 0 C90 90	CP C110 0 C110 90		
SR-D, BR-D 145		CP C145 0 M65 90	CP C145 0 M80 90	CP C145 0 M110 90		CP C145 0 C90 90	CP C145 0 C110 90	CP C145 0 C145 90	
SR-D, BR-D 200			CP C200 0 M80 90	CP C200 0 M110 90			CP C200 0 C110 90	CP C200 0 C145 90	CP C200 0 C200 90

Y-Z CONNECTION ELEMENTS

Y- Axis BR-S, BT-S, SR-S, BR-E, SR-D, BR-D = 0° Z-Axis = 90°



Y-Axis	Z-Axis											
	BR-Z 40	BR-Z 65	BR-Z 80	BR-Z 110	SR-S 40	SR-S 65	SR-S 80	SR-S 110	SR-D 90	SR-D 110	SR-D 145	
BR-S, BT-S, SR-S 40	CP M40 0 Z40				CP M40 0 ZM40							
BR-S, BT-S, SR-S 65	CP M65 0 Z40	CP M65 0 Z65			CP M65 0 ZM40	CP M65 0 ZM65						
BR-S, BT-S, SR-S 80	CP M80 0 Z40	CP M80 0 Z65	CP M80 0 Z80		CP M80 0 ZM40	CP M80 0 ZM65	CP M80 0 ZM80					
BR-S, BT-S, SR-S 110		CP M110 0 Z65	CP M110 0 Z80	CP M110 0 Z110		CP M110 0 ZM65	CP M110 0 ZM80	CP M110 0 ZM110				
BR-E 40	CP E40 0 Z40											
SR-D, BR-D 90	CP C90 0 Z40	CP C90 0 Z65			CP C90 0 ZM40				CP C90 0 ZC90			
SR-D, BR-D 110	CP C110 0 Z40	CP C110 0 Z65	CP C110 0 Z80		CP C110 0 ZM40	CP C110 0 ZM65	CP C110 0 ZM80		CP C110 0 ZC90	CP C110 0 ZC110		
SR-D, BR-D 145	CP C145 0 Z40	CP C145 0 Z65	CP C145 0 Z80	CP C145 0 Z110		CP C145 0 ZM65	CP C145 0 ZM80	CP C145 0 ZM110	CP C145 0 ZC90	CP C145 0 ZC110	CP C145 0 ZC145	
SR-D, BR-D 200			CP C200 0 Z80	CP C200 0 Z110			CP C200 0 ZM80	CP C200 0 ZM110		CP C200 0 ZC110	CP C200 0 ZC145	

CONNECTION ELEMENTS FOR CONSTRICTIONS WITH ALU PROFILES





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Linear Unit must be mounted by the aluminium profile and not at the end blocks!

MULTI AXIS SYSTEMS

We offer all neccessary fittings including brackets, clamping fixtures and adapter plates in order to build multi-axis systems. Beside standard elements we supply also custom fixing and connection elements manufactured in our workshop.



MULTI AXIS SYSTEMS



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SERVICE LIFE - LINEAR GUIDING

Mean load comparison factor fvm as a function of service life Lkm



Service life calculation:

$$L_{km} = \left(\frac{1}{f_{vm}}\right)^3 \cdot 10^2$$

Lkm Service life [km]

Safety factor fs:

$$f_s = \frac{1}{f_{vm}}$$

- fs Safety factor
- The safety factor depends on the application and its requested safety. We recommend a minimum safety factor fs = 5.0

Service life Lkm [km]

Mean load comparison factor fvm calculation:

$$fvm = \sqrt[3]{\frac{fv1^3 \times s1 + fv2^3 \times s2 + ... + fvn^3 \times sn}{s1 + s2 + ... + sn}}$$

Loading regime fv (s):



PERMISSIBLE LOAD FACTOR fp - LINEAR GUIDING

$f_{p} = \frac{ F_{y} }{ F_{py} } + \frac{ F_{z} }{ F_{pz} } + \frac{ M_{x} }{ M_{px} } + \frac{ M_{y} }{ M_{py} } + \frac{ M_{z} }{ M_{pz} } \le 1$	fp Permissible load factor Fpy Max. permissible force in the y axis N Fpz Max. permissible force in the z axis N Mpx Max. permissible moment about the x axis Nm Mpy Max. permissible moment about the y axis Nm Mpz Max. permissible moment about the y axis Nm Mpz Max. permissible moment about the y axis Nm	
--	--	--

SERVICE LIFE - BALL SCREW

Applied mean axial force Fam as a function of service life Lkm



Fam Mean axial force

Fa ii-th axial force of a given loading regime Fa (s), i \hat{i} {1,2,...,n}sii-th travel path of a given loading regime Fa (s), i \hat{i} {1,2,...,n}









i Diagrams presented above are showing theoretically determined service life of the ball screw when mean axial force Fam is taken into consideration.



• SR-S series • SR-D series



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